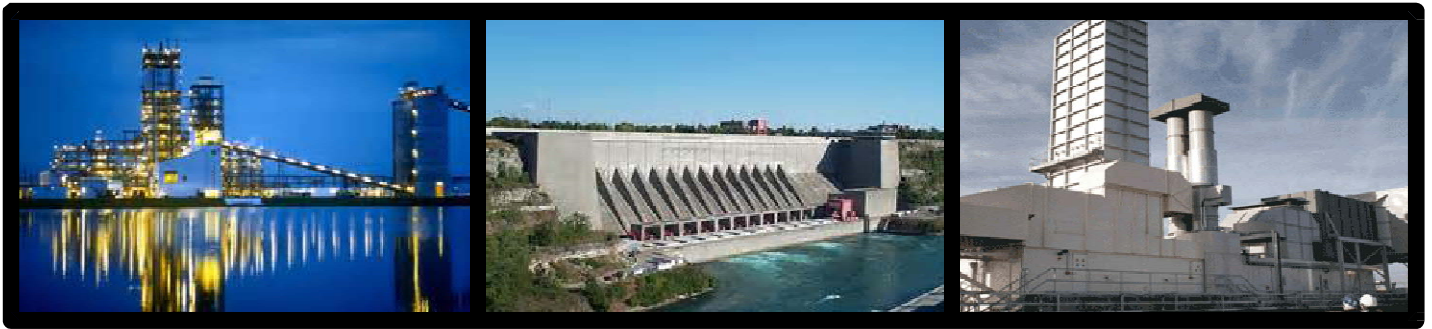




M-3425A GENERATOR PROTECTION

TEST PLAN



Conducted at:



**BECKWITH
ELECTRIC**  **CO. INC.**

6190-118th Avenue · Largo, Florida 33773-3724 U.S.A.
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Drew Welton

Vice President of Sales, Creative Technical Solutions

Beckwith Electric Company

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727-317-8899



Drew Welton is the Vice President of Sales & Creative Technical Solutions for Beckwith Electric and provides strategic leadership to the sales management team as well as creative technical solutions to our customers. Mr. Welton joined Beckwith Electric in 2016 as Director of Sales to provide strategic sales leadership and to further develop and execute sales channels.

- North American Regional Manager for OMICRON starting in 1997.
- Regional Sales Manager with Beckwith Electric. He also served as National Sales Director for Substation Automation with AREVA T&D.
- Written numerous articles on substation maintenance testing, and has conducted numerous training sessions for substation technicians and engineers at utilities and universities across North America.
- 20 year Senior Member of IEEE-PES, has been a contributor on a number of PSRC working groups, and presented at a number of industry conferences specific to power system protection and control.
- Graduate of Fort Lewis College, Durango, CO, with a Bachelor's degree in Business Administration.

1

Wayne Hartmann

Senior VP, Customer Excellence

Beckwith Electric Company

whartmann@beckwithelectric.com

904-238-3844



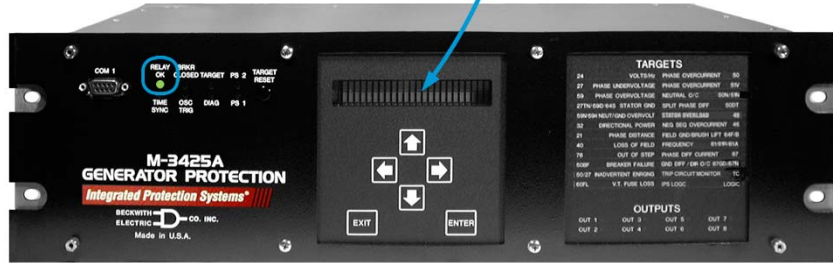
Wayne is Beckwith Electric's top strategist for delivering innovative technology messages to the Electric Power Industry through technical forums and industry standard development.

- Before joining Beckwith Electric, performed in Application, Sales and Marketing Management capacities at PowerSecure, General Electric, Siemens Power T&D and Alstom T&D.
- Provides training and mentoring to Beckwith Electric personnel in Sales, Marketing, Creative Technical Solutions and Engineering.
- Key contributor to product ideation and holds a leadership role in the development of course structure and presentation materials for annual and regional Protection & Control Seminars.
- Senior Member of IEEE, serving as a Main Committee Member of the Power System Relaying and Control Committee for over 25 years.
 - Chair Emeritus of the IEEE PSRCC Rotating Machinery Subcommittee ('07-'10).
 - Contributed to numerous IEEE Standards, Guides, Reports, Tutorials and Transactions, delivered Tutorials IEEE Conferences, and authored and presented numerous technical papers at key industry conferences.
- Contributed to McGraw-Hill's "Standard Handbook of Power Plant Engineering."

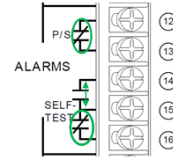
2

Normal Operation - No Targets

Display dark if there are no active targets



- Power supply fail contact = energized
 - Note: On relays with 2 power supplies installed, both must be powered up to energize this contact.
- Diagnostic Contact = coils energized, "OK" state



5

Tripped

Target, Time, Outputs, Function, Phase

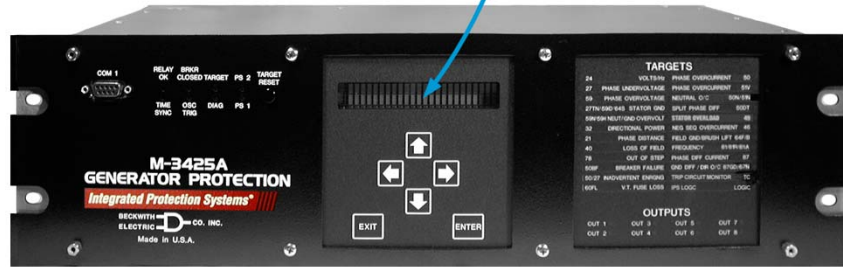


- One or more "OUTPUT" LEDs illuminated

6

Trip Cleared and Target Present

Target, Time, Outputs, Function, Phase



•All "OUTPUT" LEDs Extinguished

7

Relay failed internal self diagnostics

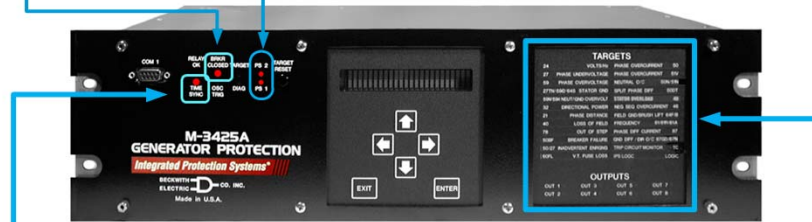


- If the "Relay OK LED" is extinguished, the relay is not in service.
 - Contact the factory if a "System Halt" message is displayed or the "Relay OK" LED is extinguished.
- Resetting the relay may temporarily remove the error but may result in a false trip or no trip operation.
- Do not press any HMI buttons while the relay is in diagnostic mode.

8

Other front panel indicators

- **Breaker Closed:** Normally on when Input 1 is open
- **PS1 and PS2:** On when the associated power supply is on.



- **Time Sync:** On when IRIG-B signal is applied. No setting is required.
- **Target:** On when most recent event is not reset

Front panel controls



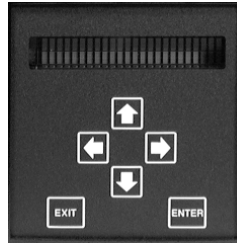
Target Reset Button:

- **Button Released:** Target module and HMI display the most recent event information.
- **Button Pressed and Released:** LED test then targets are reset *IF ALL TRIPPED FUNCTIONS ARE RESET.*
- **Button Pressed and Held:** Target module displays functions that are currently picked up.

Note: Output LED's always display real time status of output contacts.

Front Panel Controls: HMI Operation

- Access by pressing any button after the Power On Self Test terminates.
- The selected menu item appears in capital letters.
- Press the **RIGHT** and **LEFT** arrows to move between menu items.
- Press **ENTER** to move into a submenu or item
- Press **EXIT** move out of a submenu.
- The **UP** and **DOWN** arrows are used to change values.



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HMI Operation

VOLTAGE RELAY
VOLT curr freq v/hz →

- 27 Phase Undervoltage
- 59 Phase Overvoltage
- 27TN Neutrl Undervolt
- 59X Overvoltage
- 59N Neutral Overvoltage
- 59D Volt. Diff. 3rd Har.

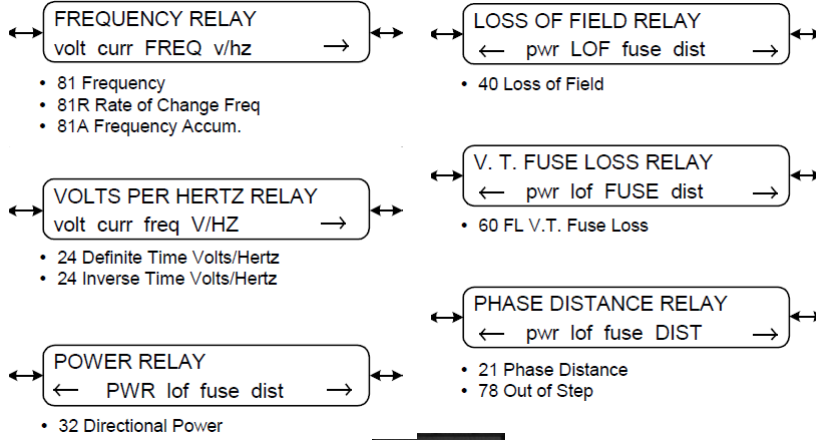
CURRENT RELAY
volt CURR freq v/hz →

- 46 Neg Seq Overcurrent
- 50 Inst Overcurrent
- 50/27 Inadvertent Energizing
- 50BF Breaker Failure
- 50DT Def. Time Overcurr
- 50N Inst Overcurrent
- 51N Inv Time Overcurrent
- 49 Stator Overload
- 51V Inv Time Overcurrent
- 87 Differential Overcurr
- 87GD Gnd Diff Overcurr
- 67N Res Dir Overcurr

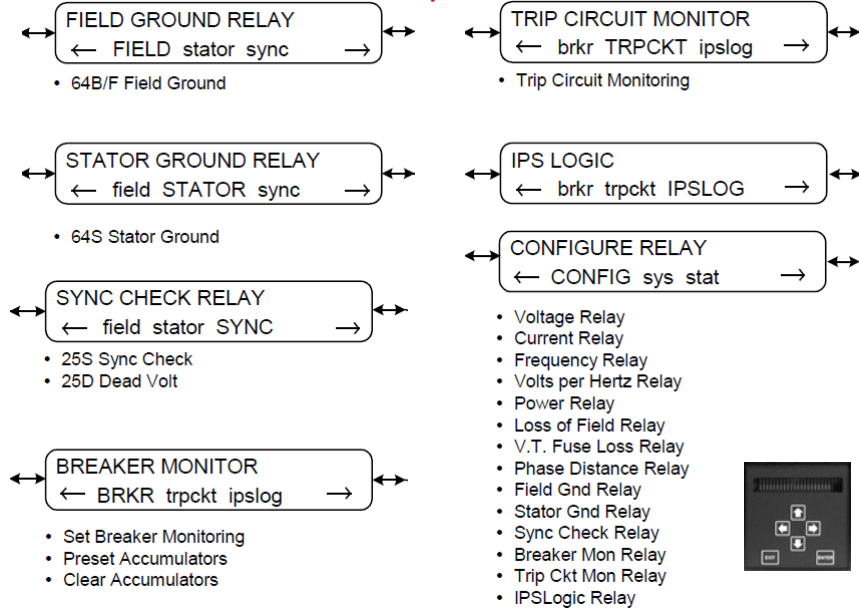


12

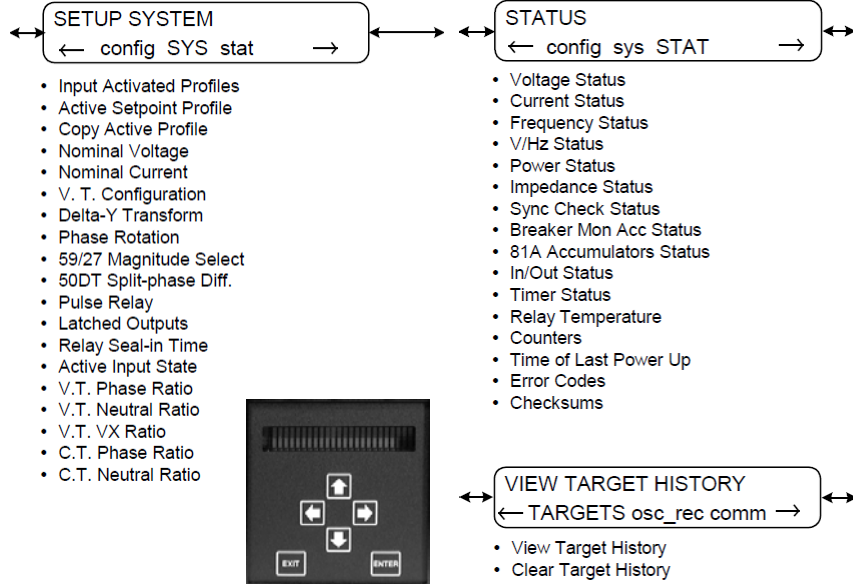
HMI Operation



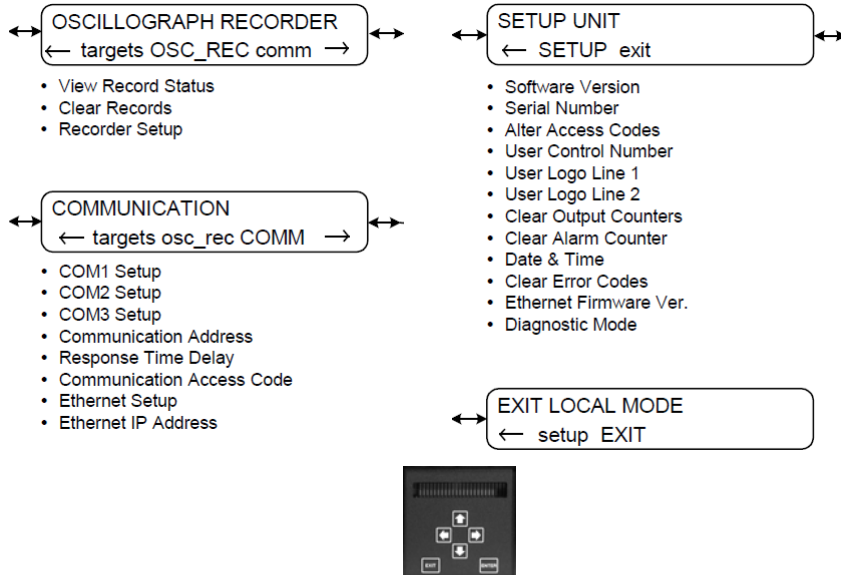
HMI Operation

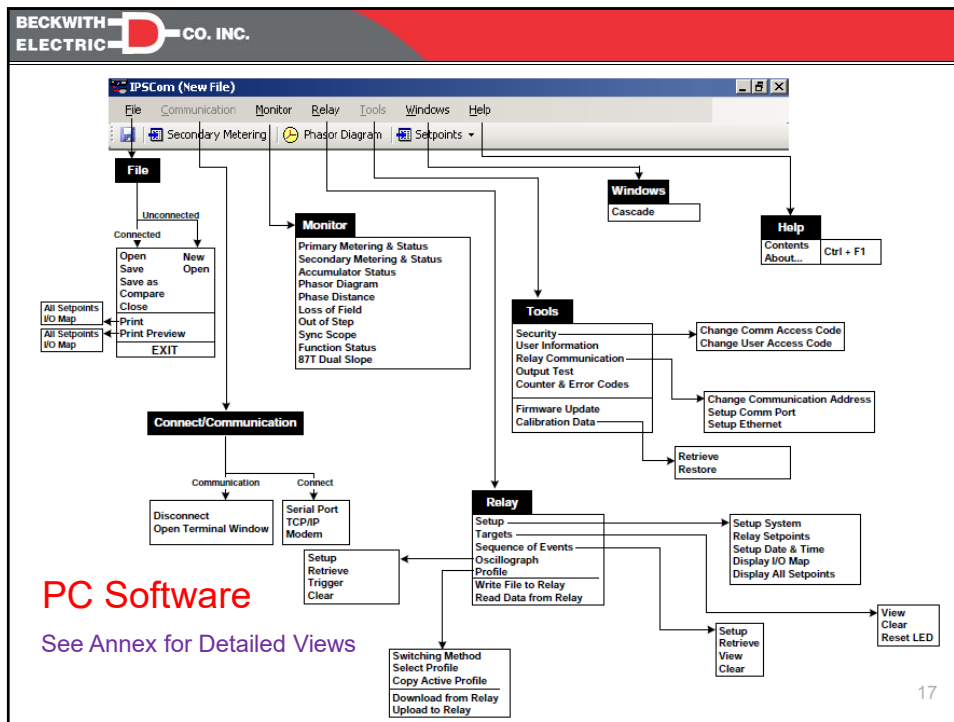


HMI Operation



HMI Operation





BECKWITH ELECTRIC CO. INC. **M-3425A IPSCOM Operation**

Working Offline

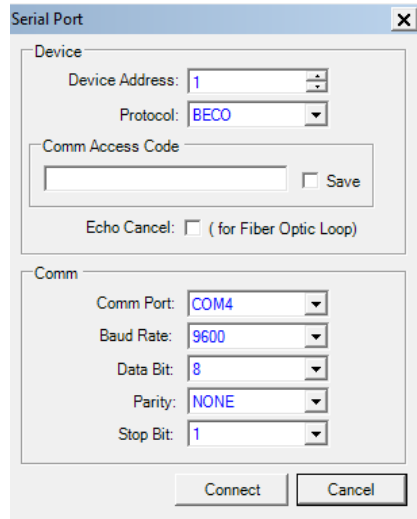
- Used to create, view, or modify relay setting files

- For a new Setting file:**
 - Select File\New
 - Set Unit type, frequency, CT, and Phase Rotation
- For and Existing File:**
 - Select File\Open
 - Pick the file to be opened
- To Save, use the Save or Save As commands**

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Working Online

•Used to communicate directly with a relay via 232, 485, modem, or TCP/IP



- PC Port - Serial port on the PC
- The following must be set to match the relay settings :
 - Baud Rate-9600 standard
 - Access Code-Defaults disabled
 - Address-232/485 network address
- For Modem or TCP/IP communications, press the appropriate buttons and set the parameters

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Periodic Maintenance: General

All our relays incorporate self diagnostic hardware and continuously run a number of self diagnostic routines.

We highly recommend the relay self test contact as well as the power supply fail contact be connected as your application dictates.

Our minimum recommended periodic maintenance focuses on those components that cannot be checked by the internal diagnostic routines:

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Periodic Maintenance: Critical Checks

Each Maintenance Outage:

- 1) **Relay Trip Test:** *Use the diagnostic feature to force a trip. Verify the breaker opens.*
- 2) **Relay Diagnostics:** *Perform relay diagnostic checks which check the operation of the status inputs and outputs.*
- 3) **Breaker Position Sensing:** *Verify the breaker's position contact is working correctly.*

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Digital Relay Self-Diagnostics

What it covers:

- Microprocessor hand-shaking
- ADC
- Power supply
- Communication failures
- Watchdogs
- Firmware flash failures

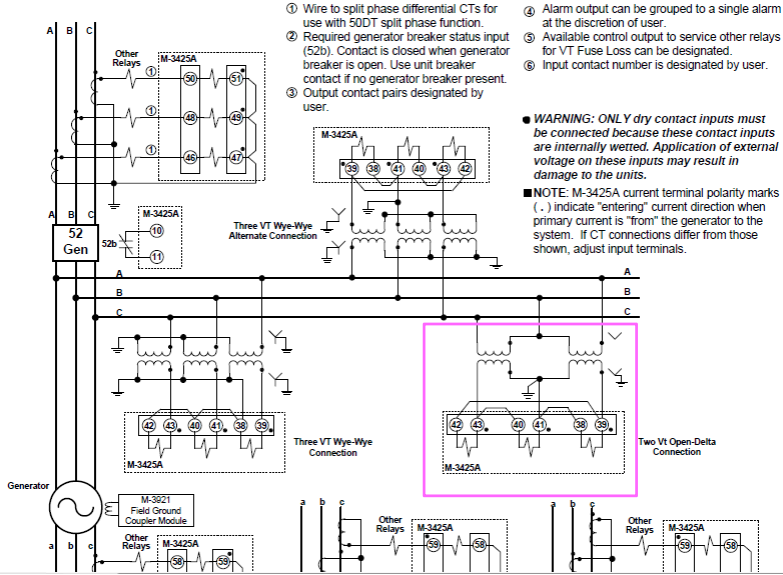
What it does not cover:

- Relay contacts
- Internal CT PT circuits
- Improper wiring
- **Misapplied logic**
- **Incorrect settings**

- In all cases, relay failures covered by self-diagnostics can alert operators through an alarm contact.
- The relay can then take itself out of service to avoid misoperations.

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3-Line Diagram Partial: A



3-Line Diagram Partial: B



1. **Energize the relay**

- Verify which power supply installed by checking the marks on the back of the relay
- Apply the proper voltage and check the following:
 - Power supply contact drops out (if 2 power supplies are installed, both must be energized to clear power fail contact)
 - Diagnostic contact drops out after POST testing completes
 - "Relay OK" LED on/flashing

Note: Do not press any buttons while the Power On Self Test is in process.

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1. Energize the relay
2. Set the clock

3. **Install the relay setting using IPScom**

From a File:

- Connect to the relay
- Relay Menu ⇒ Write File To Relay
- Use the browsing control to select the file
 - Note: The file save must be for the same relay type and have the same phase rotation for this feature to work
- Relay Menu ⇒ Setup ⇒ Sequence of Events ⇒ Setup. Enter the settings
- Relay Menu ⇒ Setup ⇒ Oscilloscope ⇒ Setup. Enter the settings

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1. Energize the relay
2. Set the clock
- 3. Install the relay setting using IPScom**

From a Setting Sheet:

- Connect to the relay
- Relay Menu ⇒ Setup ⇒ Setup System. *Enter the settings.*
- Relay Menu ⇒ Setup ⇒ Setpoints ⇒ Configure. *Enter the settings.*
- Relay Menu ⇒ Setup ⇒ Sequence of Events ⇒ Setup. *Enter the settings.*
- Relay Menu ⇒ Setup ⇒ Oscilloscope ⇒ Setup. *Enter the settings*
- Save the file by selecting File ⇒ Save As.

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System Setup Settings:

These settings are used throughout the relay.

The screenshot shows the 'Setup System' dialog box with the following settings:

Setting	Value	Min	Max	Units
Nominal Voltage	120.0	50.0	140.0	(V)
Nominal Current	3.95	0.50	6.00	(A)
Phase Rotation	<input checked="" type="radio"/> ABC	<input type="radio"/> ACB	<input type="radio"/> DFT	
59/27 Magnitude Select	<input checked="" type="radio"/> RMS	<input type="radio"/> Enable	<input type="radio"/> Delta-AC	
50DT Split Phase Diff	<input checked="" type="radio"/> Disable	<input type="radio"/> Line to Ground	<input type="radio"/> Line-Ground to Line-Line	
Delta-Y Transform	<input type="radio"/> Disable	<input checked="" type="radio"/> Delta-AB		
V.T. Configuration	<input checked="" type="radio"/> Line to Line			
V.T. and C.T. Ratio				
V.T. Phase Ratio	142.0	1.0	6550.0	(:1)
V.T. Neutral Ratio	60.0	1.0	6550.0	(:1)
V.T. VX Ratio	208.0	1.0	6550.0	(:1)
C.T. Phase Ratio	3600	1	65500	(:1)
C.T. Neutral Ratio	5000	1	65500	(:1)

Buttons: Save, Cancel

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Basic Settings (cont.):

VT Configuration	Nominal Voltage	Used
L-G	$V_{nom} = GEN V_{LL} / (1.732 * VTR)$	(21, 32, 40, 46, 50/27, 51V)
L-L	$V_{nom} = GEN V_{LL} / (VTR)$	
L-G to L-L	$V_{nom} = GEN V_{LL} / (VTR)$	

Nominal Current

$$I_{nom} = GEN VA / (1.732 * GEN V_{LL} * CTR)$$

(21, 32, 40, 46, 50/27, 51V, 87)

Delta-Y Transform (21, 51V):

Determines calculation used for 21 and 51V functions

Basic Settings (cont.):

Input Active State (all functions using blocking or external initiate):

- Sets the input logic to assert when connected contact is closed or open.
 - Note: For element blocking when GEN CB is open
 - 52/b should be set to *active closed*
 - 52/a to *active open*.

VT Configuration

- Line-to-Ground: Used with Y connected VTs
- Line-to-Line: Used with Delta or Open Delta VTs
- Line-to-Ground to Line-to-Line: Used with Y connected VTs
 - With this setting the relay internally calculates the equivalent phase to phase voltage and uses that voltage for trip decisions while maintaining L-G voltages for the oscillography.
 - *In High-Z Grounded Generators, this setting prevents the 59 and 27 elements from tripping on stator ground faults.*

Basic Settings (cont.):**59/27 Magnitude Select:**

- Adjusts the calculation used for the overvoltage, undervoltage, and the inadvertent energization element.
- In generator applications, this should be set to RMS

RMS averages the most recent 8 cycles of data

- If the voltage is 0V, there are no zero crossings and the relay holds the most recent values for 30cyc.
- After this time the relay performs the measurement on the most recent 8 cycles of data.
- This results in accurate measurements over a wide frequency but sacrifices speed.

DFT averages the most recent 16 samples (16.7mSec at 60Hz) and calculates the voltage once per cycle.

- This results in faster operation but accuracy is limited to a narrower frequency range.

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Basic Settings (cont.):**Phase Rotation:**

This setting adjusts nominal phase rotation.

- We do not recommend reversing the CT and PT connections to change the rotation.
- Using the software switch will result in proper phase targeting.

50DT Split phase Differential:

Used for split phase hydro applications.

- Changes IA, IB, and IC metering labels
- Disables 87G

Relay Seal In Time:

- *Normal*: Sets the minimum amount of time a relay output contact will be closed after tripping element deassertion.
- *Pulse*: Sets the relay output contact closure time duration regardless of if the tripping element maintains assertion.
- *Latched*: Relay output contact will remain closed until relay is reset

34

Connect the relay voltages for today's training:

M-34XX Test Connection for L-L, or Open Delta

Test Set Connections:

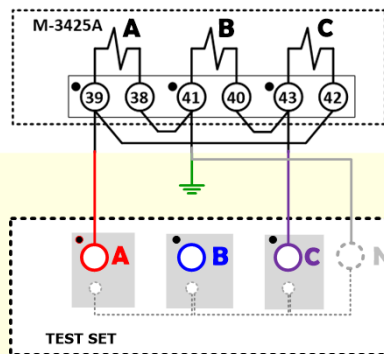
Single Phase Voltage

Phase A+ to terminal # 38
 Phase B+ (None)
 Phase C+ to terminal # 43
 Return A,B,C to terminal #39

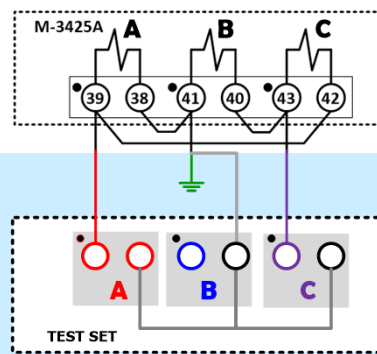
V+ to #45
 V1 to #44

On the relay only:
 Jumper #38 to #41
 Jumper #39 to #42
 Jumper #40 TO #43

Phase Voltage Connections



- For Test Sets with *internally connected* source neutrals.
- Neutral terminal on test set not connected to relay.



- For Test Sets with *externally connected* source neutrals.
- Neutral terminals on Test Set not connected to relay.

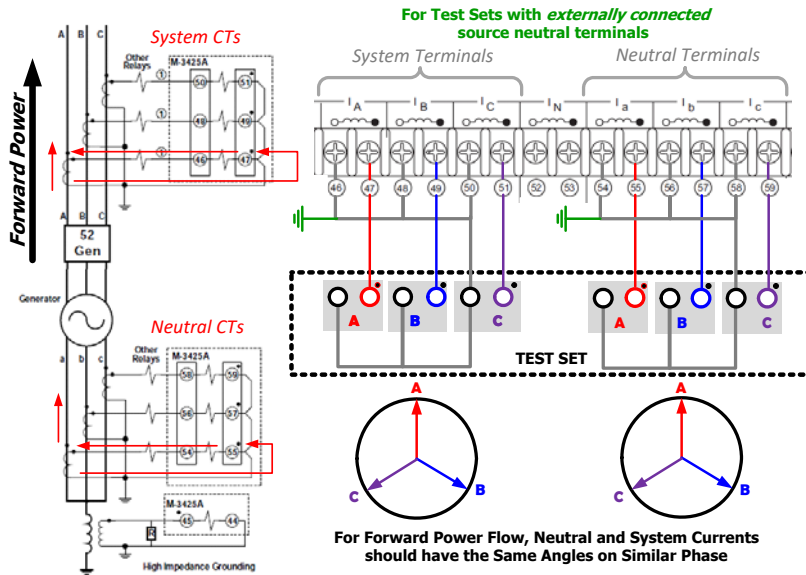
Connect the relay **currents** for today's training:

M-34XX Test Connection

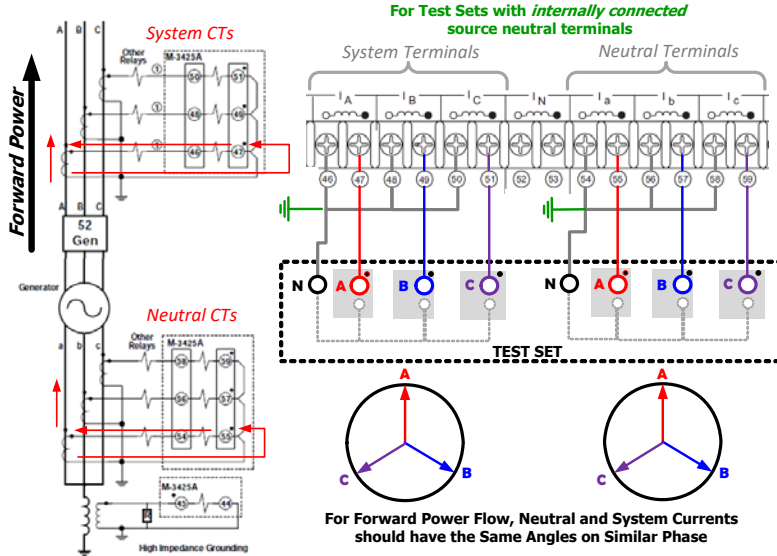
Test Set currents 1	M-3425A	Test Set currents 2	M-3425A
IA	IA +	IA	Ia +
IB	IB +	IB	Ib +
IC	IC +	IC	Ic +
IN	Jumper	IN	Jumper
<i>Neutral Terminals</i>		<i>Output Terminals</i>	

Balance currents for all voltage-type, power and overcurrent tests, or disable 87 elements

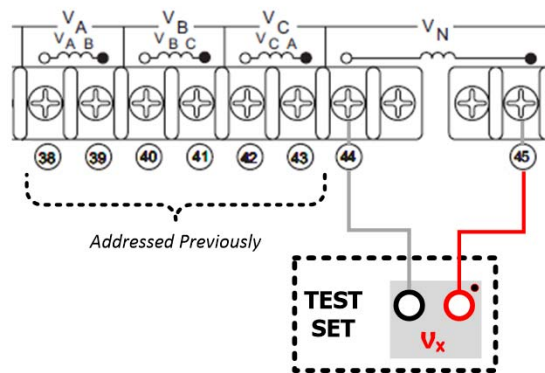
Phase Current Connections



Phase Current Connections



Neutral Voltage Connection



Apply nominal quantities and check the metering

Delta-Connected PTs with Line-Line Relay Setting

Secondary Metering

Currents (A)				Voltages (V)				Impedance (Ohm)							
Phase A	0.000	Phase a	3.931	AB	119.7	AB R	17.69	AB X	0.12	BC R	17.40	BC X	0.10		
Phase B	0.000	Phase b	3.939	BC	119.6	BC X	0.10	CA R	17.66	CA X	-0.28	Pos. Seq. R	17.72	Pos. Seq. X	0.63
Phase C	0.000	Phase c	3.936	CA	119.7	Neutral	0.0	Pos. Seq.	119.6	Neg. Seq.	0.0	Zero Seq.	0.0	VX	0.0
Neutral	0.000	I diff G	0.00	Neutral	0.0	Power (p.u.)		Frequency		Misc		Status			
Pos. Seq.	3.933	A-a diff	3.94	Pos. Seq.	119.6	Real	0.994	Frequency (Hz)	60.00	Power Factor	1.00 LAG	Breaker Closed	Targets		
Neg. Seq.	0.004	B-b diff	3.93	Neg. Seq.	0.0	Reactive	0.037	V/Hz (%)	99.8	Brush V. (mV)	239	Osc Triggered	IRIGB Sync		
Zero Seq.	0.002	C-c diff	3.94	Zero Seq.	0.0	Apparent	0.994	ROCOF (Hz/s)	0.00	Field Insul. (Ohm)	<1K				
49 #1	2.41	49 #2	2.20	VX	0.0										

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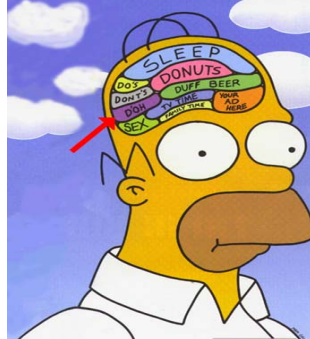
Incorrect Wiring: VA and VB Rolled

Secondary Metering

Currents (A)				Voltages (V)				Impedance (Ohm)					
Phase A	0.000	Phase a	0.000	AB	119.7	AB R	81.91	AB X	81.91	BC R	-8.54	BC X	15.16
Phase B	0.000	Phase b	3.933	BC	119.6	BC X	15.16	CA R	17.53	CA X	-0.25	Pos. Seq. R	-0.16
Phase C	0.000	Phase c	3.934	CA	119.7	Neutral	0.0	Pos. Seq.	0.0	Neg. Seq.	119.8	Zero Seq.	0.0
Neutral	0.000	I diff G	0.00	Neutral	0.0	Power (p.u.)		Frequency		Misc		Status	
Pos. Seq.	2.623	A-a diff	0.02	Pos. Seq.	0.0	Real	-0.021	Frequency (Hz)	DISABLED	Power Factor	0.04 LAG	Breaker Closed	Targets
Neg. Seq.	1.313	B-b diff	3.95	Neg. Seq.	119.8	Reactive	0.574	V/Hz (%)	99.8	Brush V. (mV)	239	Osc Triggered	IRIGB Sync
Zero Seq.	1.313	C-c diff	3.94	Zero Seq.	0.0	Apparent	0.573	ROCOF (Hz/s)	0.00	Field Insul. (Ohm)	<1K		
49 #1	3.43	49 #2	3.27	VX	0.0								

What shows the relay is wired wrong?

How Do We Test?



“Thinking logically as to how a relay responds in a faulted condition helps to visualize a proper test sequence”
--Drew Welton



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How Do We Test?

Utilize proper test sequences to avoid associated logic settings:

1. Apply proper pre-fault conditions
 - Nominal V, I
 - 52/a=closed, 52/b=open, contacts in non-faulted state
 - Apply long enough for reset from lockouts if needed
2. Faulted values applied
3. Post-fault State
 - V, I faulted value removed (I=0), (V=0 or Nominal, location of the VT)
 - Breaker contact status changes (52/a=open, 52/b=closed)

44

44

Rules of the Ramp!!

Always start with nominal values!

- 1) Times between each ramp state is > time delay for the element
- 2) Step size is < than the tolerance of the element

Rules of the Timing!!

- 1) Always start with nominal values, lock
- 2) Change to below or above set point
- 3) Unlock fault values, check timing

45
45

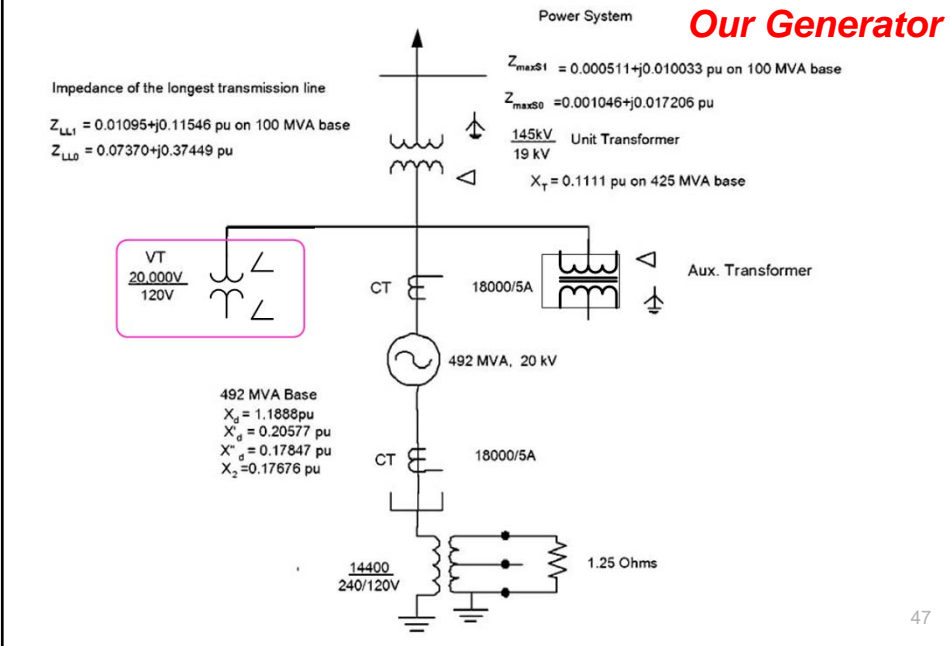
Overall Test Plan

1. Pre-Startup Tasks and Relay Setup
2. Negative Sequence (46)
3. Loss of Synchronism (78)
4. Stator Ground Overvoltage (59N)
5. Third Harmonic Neutral Undervoltage (27TH)
6. Oscillography and SOE Demo

⇒W

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Our Generator



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Calculations for Our Generator

$$Z_{base} = (GEN \text{ kV}^2 / GEN \text{ MVA}) / (1.73 * kV_{base})$$

$$Z_{base} = (20 \text{ kV}^2 / 492 \text{ MVA}) / (1.73 * 20 \text{ kV}_{base})$$

$$Z_{base} = 0.813 \Omega_{pri}$$

$$I_{base} = (MVA * 1000) / (1.73 * kV_{base})$$

$$I_{base} = (492 \text{ MVA} * 1000) / (1.73 * 20 \text{ kV}_{base})$$

$$I_{base} = 14,219 A_{pri}$$

$$VTR = 20,000V / 120V = 166.7$$

$$CTR = 18,000A / 5A = 3,600$$

$$CTR/VTR = 21.5996$$

$$I_{base \text{ sec}} = I_{pri} / CTR$$

$$I_{base \text{ sec}} = 14,219_{pri} / 3,600$$

$$I_{base \text{ sec}} = 3.945 A_{sec}$$

$$V_{LL \text{ sec}} = 120V$$

$$V_{LG \text{ sec}} = V_{LL \text{ sec}} / 1.73$$

$$V_{LL \text{ sec}} = 69.28V_{sec}$$

$$Z_{Base \text{ sec}} = Z_{Base \text{ pri}} * (CTR / VTR)$$

$$Z_{Base \text{ sec}} = 0.813 \Omega_{pri} * (3,600 / 166.7)$$

$$Z_{Base \text{ sec}} = 17.55 \Omega_{sec} \text{ (1pu)}$$

Reactances per unit (492 MVA Base)

$$X_d = 1.1888 \text{ pu}$$

$$X'_d = 0.20577 \text{ pu}$$

$$X'_d = 0.20577 \times 17.56 = 3.613 \Omega$$

$$X_{TG} = 0.11607 \times 17.56 = 2.04 \Omega$$

$$X_{max \text{ SG1}} = 0.04035 \times 17.56 = 0.7086 \Omega, \beta = 90^\circ$$

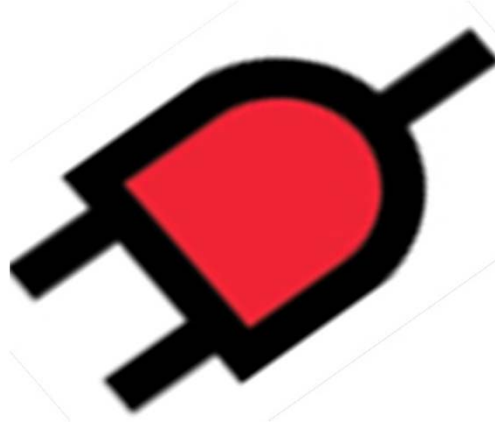
$$Z_{Base \text{ sec}} = Z_{Base \text{ pri}} * (CTR / VTR)$$

$$Z_{Base \text{ sec}} = 0.813 \Omega_{pri} * (3,600 / 166.7)$$

$$Z_{Base \text{ sec}} = 17.55 \Omega_{sec} \text{ (1pu)}$$

48

Negative Sequence Overcurrent (46)



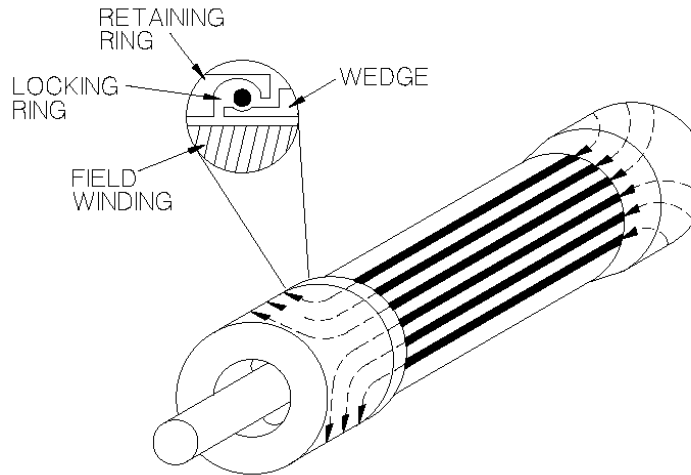
49

46: Negative Sequence Current

- Typically caused by open circuits in system
 - Downed conductors
 - Stuck poles switches and breakers
- Unbalanced phase currents create negative sequence current in generator stator and induces a double frequency current in the rotor
- Induced current (120 Hz) into rotor causes surface heating of the rotor

50

Rotor End Winding Construction



Currents Flow in the Rotor Surface

51

Negative Sequence Current: Constant Withstand Generator Limits

➤ Salient Pole

- With connected amortisseur 10%
- With non-connected amortisseur 5%

➤ Cylindrical

- Indirectly 10%
- Directly cooled - to 960 MVA 8%
 - ✓ 961 to 1200 MVA 6%
 - ✓ 1200 to 1500 MVA 5%

52

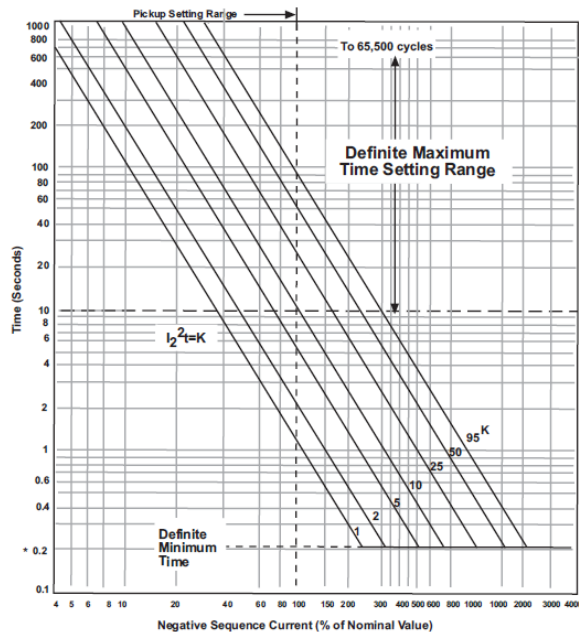
Negative Sequence Current: Constant Withstand Generator Limits

➤ Nameplate

- Negative Sequence Current (I_2) Constant Withstand Rating
- "K" Factor

- Where: $I_2^2 T = K$

53



Generator Ratings

Typical
K Values
Salient Pole
Generators
40

Cylindrical
Generators
30

54

46: Negative Sequence Electromechanical Relays

- Sensitivity restricted and cannot detect I_2 levels less than 60% of generator rating
- Fault backup provided
- Generally insensitive to load unbalances or open conductors

55

46: Negative Sequence Digital Relay

- Protects generator down to its continuous negative sequence current (I_2) rating vs. electromechanical relays that don't detect levels less than 60%
- Fault backup provided
- Can detect load unbalances
- Can detect open conductor conditions
- Should provide thermal time reset as I_2 causes heating

56

46: Setting

Type of generator	Permissible I_2 (percent)
Salient pole	10
With connected amortisseur windings	10
With non-connected amortisseur windings	5
Cylindrical rotor	
Indirectly cooled	10
Directly cooled—Up to 350 MVA	8
—351 MVA to 1250 MVA	$8 - (MVA - 350) / 300$
—1251 MVA to 1600 MVA	5

492 MVA;
Cylindrical

Type of generator	Permissible $I_2^2 t$
Salient pole generator	40
Synchronous condenser	30
Cylindrical rotor generators	
Indirectly cooled	30
Directly cooled (0 MVA to 800 MVA)	10
Directly cooled (801 MVA–1600 MVA)	See Figure 4-39.

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46: Setting

The screenshot shows the '46: Negative Sequence Overcurrent' configuration window. It is divided into two sections: 'Definite Time' and 'Inverse Time'. Both sections have 'Pickup' and 'Time Delay' fields. The 'Definite Time' section has a 'Time Delay' of 10 and 'Blocking Inputs' 1-14. The 'Inverse Time' section has a 'Time Dial' of 10, a 'Maximum Time' of 60000, and a 'Reset Time' of 10. Below the settings window, a secondary metering display shows: Pos. Seq. 3.939, Neg. Seq. 0.000, and Zero Seq. 0.002.

- Definite Time used for Alarming; using short timer for testing
- Inverse Time used for Protection; using short reset time for testing

Testing the 46 Element, Def. Time

Pick up = 5% of Nominal Current, $3.95 \times .05 = .198$
Neg. Sequence Component

Pos. Seq.	3.939
Neg. Seq.	0.000
Zero Seq.	0.002

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 *	60.000 Hz
VB	0.000 V	0.00 *	60.000 Hz
VC	120.0 V	90.00 *	60.000 Hz
V Fault	2.000 V	0.00 *	180.000 Hz
neutral a	3.950 A	0.00 *	60.000 Hz
neutral b	3.950 A	-120.00 *	60.000 Hz
neutral c	3.950 A	120.00 *	60.000 Hz

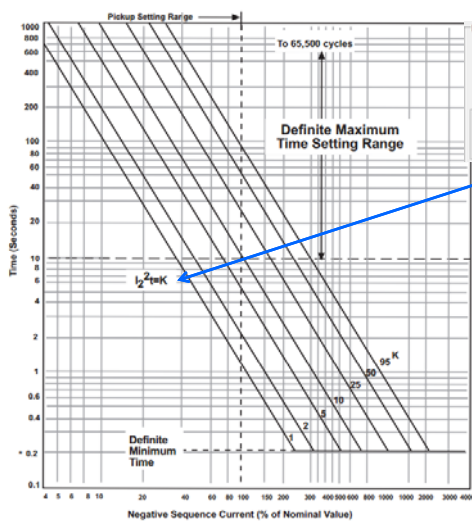
trip 2 9.696 cy

Alarm Contact

Pos. Seq.	3.929
Neg. Seq.	0.198
Zero Seq.	0.198

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 *	60.000 Hz
VB	0.000 V	0.00 *	60.000 Hz
VC	120.0 V	90.00 *	60.000 Hz
V Fault	2.000 V	0.00 *	180.000 Hz
neutral a	3.950 A	-8.75 *	60.000 Hz
neutral b	3.950 A	-120.00 *	60.000 Hz
neutral c	3.950 A	120.00 *	60.000 Hz

Test Sequence for 46-Inverse Time



Inverse Time

Pickup: 8 3 100 (%) Disable

Time Dial: 10 1 95

Maximum Time: 6000 600 65500 (Cycles)

Reset Time: 10 1 600 (Sec=6)

Outputs: 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24

Blocking Inputs: FL 1 2 3 4 5 6 7 8 9 10 11 12 13 14

Use this formula like so:
 $I_{\text{fault}} / I_{\text{nom}} (6/3.95 = 1.52)$
 $1.52 \text{ squared} = 2.3$
 $TD 10 / 2.31 = 4.35 \text{ sec Pick up time}$

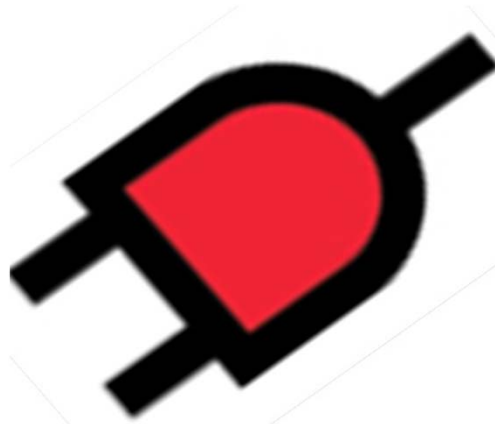
SO:
 @ 6 amps trip time = 4.35 sec
 @ 8 amps trip time = 2.44 sec

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 *	60.000 Hz
VB	0.000 V	0.00 *	60.000 Hz
VC	120.0 V	90.00 *	60.000 Hz
V Fault	2.000 V	0.00 *	180.000 Hz
neutral a	6.000 A	0.00 *	60.000 Hz
neutral b	6.000 A	120.00 *	60.000 Hz
neutral c	6.000 A	-120.00 *	60.000 Hz

Roll Ph b and c

Loss-of-Synchronism (78)

aka: Out-of-Step



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Generator Out-of-Step Protection (78)

- Types of Instability
 - Steady State: Steady Voltage and Impedance (Load Flow)
 - Transient: Fault, where voltage and impedance change rapidly
 - Dynamic: Oscillations from AVR damping (usually low f)
- Occurs with unbalance of load and generation
 - Short circuits that are severe and close
 - Loss of lines leaving power plant (raises impedance of loadflow path)
 - Large losses or gains of load after system break up
- Generator accelerates or decelerates, changing the voltage angle between itself and the system
- Designed to cover the situation where electrical center of power system disturbance passes through the GSU or the generator itself
- More common with modern EHV systems where system impedance has decreased compared to generator and GSU impedance

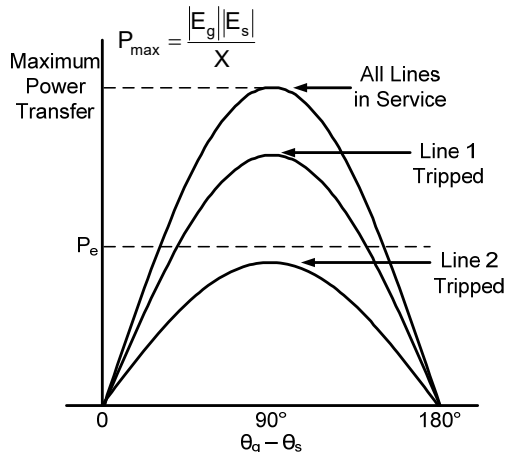
62

Generator Out-of-Step Protection (78)

- When a generator goes out-of-step (synchronism) with the power system, high levels of transient shaft torque are developed.
- If the pole slip frequency approaches natural shaft resonant frequency, torque produced can break the shaft
- High stator core end iron flux can overheat and short the generator stator core
- GSU subjected to high transient currents and mechanical stresses

63

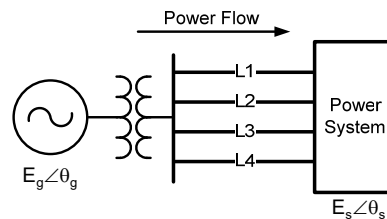
Stability



Power Transfer Equation

$$P_e = \frac{|E_g||E_s|}{X} \sin(\theta_g - \theta_s)$$

- E_s - System Voltage
- E_g - Generator Voltage
- θ_s - System Voltage Phase Angle
- θ_g - Generator Voltage Phase Angle
- P_e - Electrical Power

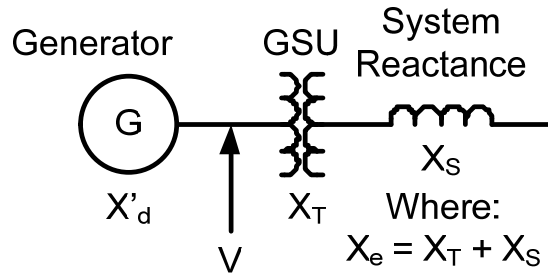


For maximum power transfer:

- Voltage of GEN and SYSTEM should be nominal – Faults lower voltage
- Impedance of lines should be low – lines out raise impedance

64

Out of Step: Generator and System Issue

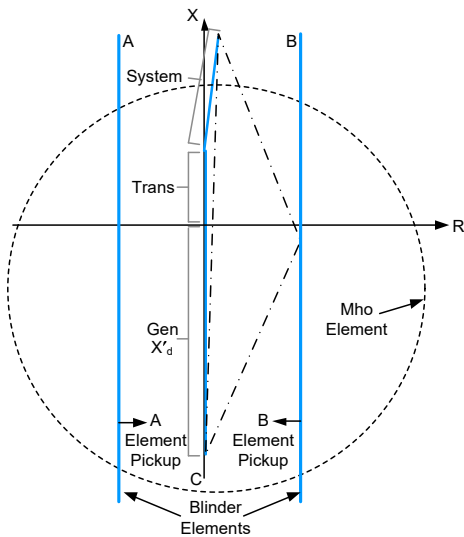


Power Transfer Equation

$$P_e = \frac{|E_g||E_s|}{X} \sin(\theta_g - \theta_s)$$

65

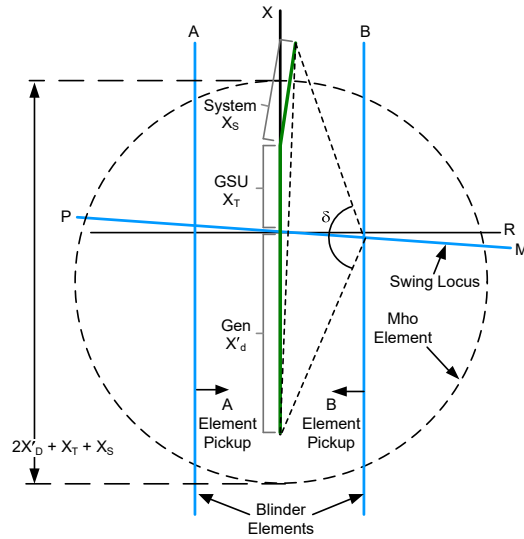
Single Blinder Scheme



- One pair of blinders (vertical lines)
- Supervisory offset mho
- Blinders limit reach to swings near the generator

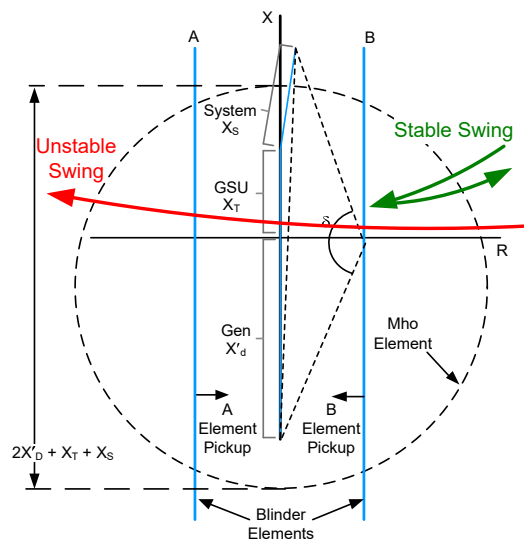
66

Graphical Method: 78



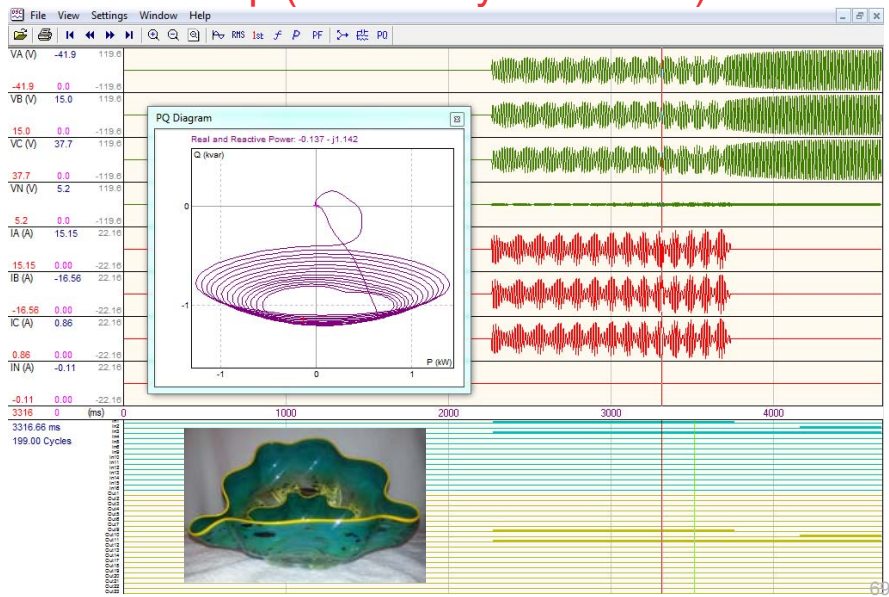
67

Graphical Method: 78



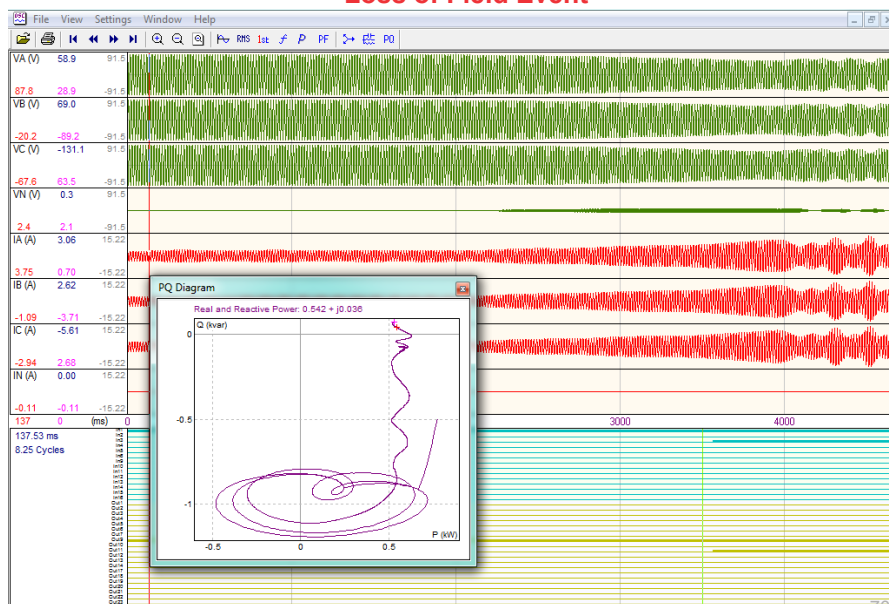
68

Out-of-Step (Loss of Synchronism) Event

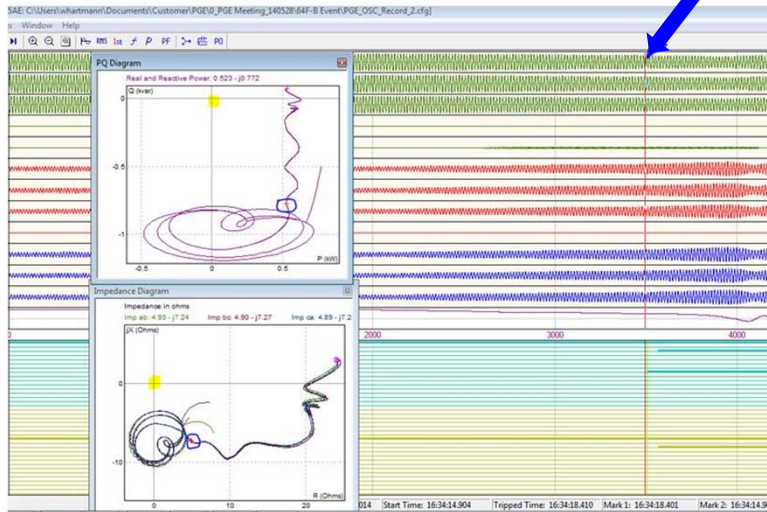


Generator Protection

Loss of Field Event

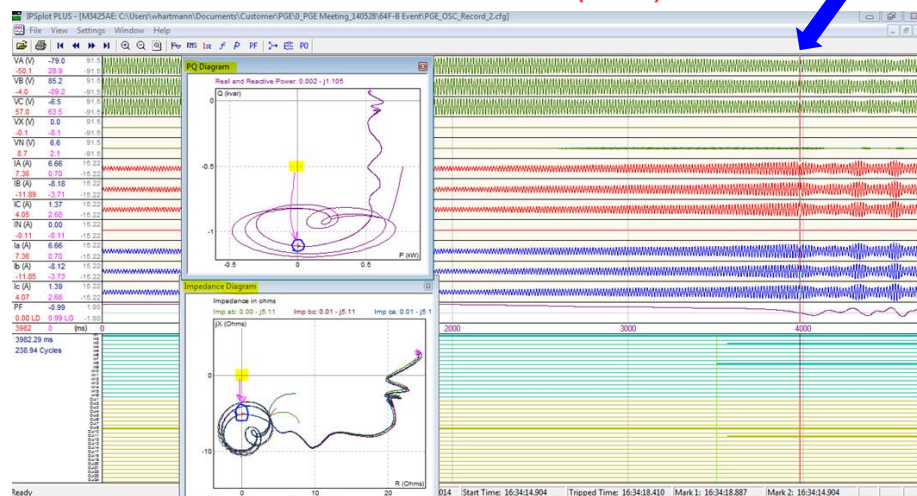


Loss of Field Event (3 of 6)



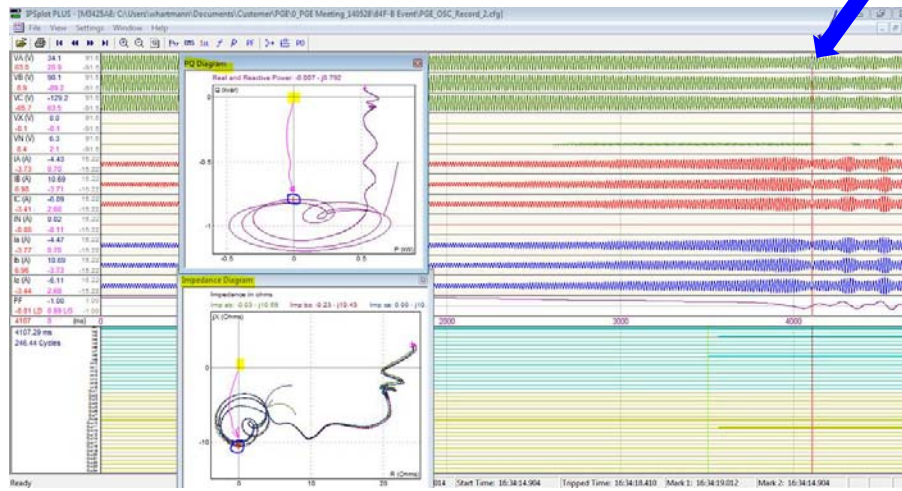
- We have lost field, and the impedance/power plan plots show we are still outputting watts but are sinking lots of VAR
- This is JUST before the machine goes into asynchronous operation with a slip 73

Loss of Field Event (4 of 6)



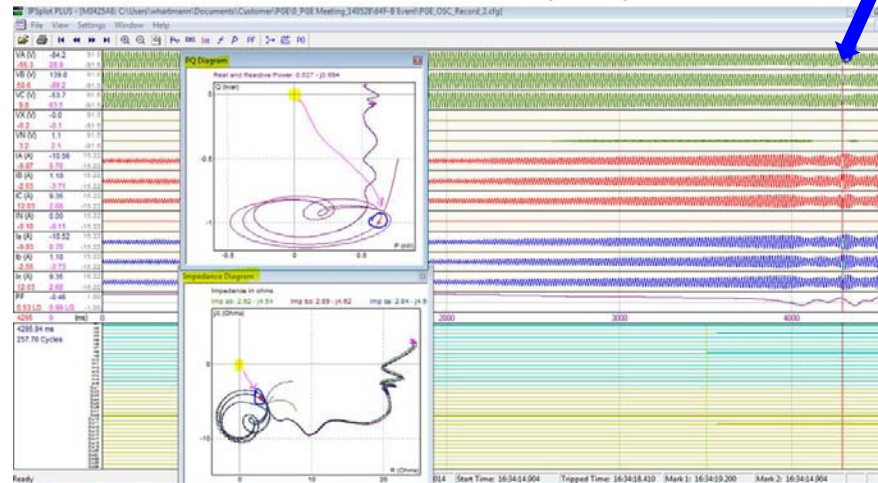
- We have lost field, and the impedance/power plan plots show we are NOT putting out ANY watts and sucking a lot of VAR. The machine is slipping a pole.
- At the instant shown, all the current into the machine is reactive (VAR sink).

Loss of Field Event (5 of 6)



- The machine is slipping a pole. We are into the first slip cycle.

Loss of Field Event (6 of 6)



- The machine is slipping a pole. We are into the first slip cycle.

Generator Out-of-Step Protection (78)

Dependability Concerns

- Positive sequence quantities used to maintain security and accuracy over a wide frequency range.
- Required to operate correctly (and not misoperate) with wide frequency variations possible during power swing conditions
 - Must work properly from 50 to 70 Hz (60 Hz systems).

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78: Setting

$$Amps = \frac{KVA \times 1000}{\sqrt{3} \times Volts}$$

$$14202.8A_{pri} = \frac{492,000KVA \times 1000}{1.73 \times 20,000V}$$

$$3.945A_{sec} = 14,202.8 / 18,000:5 \text{ (3600 CTR)}$$

$$V_{LL_B_relay} = VT \text{ primary voltage} / VT \text{ ratio} = 20,000 / 166.67 = 120 \text{ V}$$

$$V'_{LN_B_relay} = 11547 / 166.67 = 69.28 \text{ V} \quad [120V_{LL} / 1.73 = 69V_{LN}]$$

$$Z_{B_relay} = \frac{V_{LN_B_relay}}{I_{B_relay}} = 69.28 / 3.95 = 17.56 \Omega$$

$$X'_d = 0.20577 \times 17.56 = 3.613 \Omega, X_{TG} = 0.11607 \times 17.56 = 2.04 \Omega$$

$$X_{max\ SG1} = 0.04035 \times 17.56 = 0.7086 \Omega, \beta = 90^\circ$$

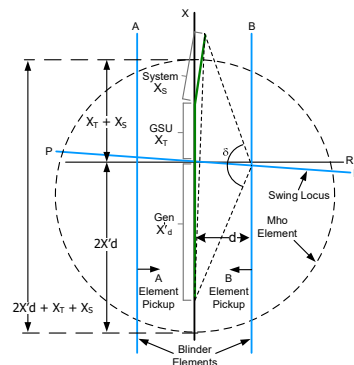
$$\text{The blinder distance (d)} = ((X'_d + X_{TG} + X_{max\ SG1}) / 2) \times \tan(90 - (\delta/2))$$

$$\text{For } \delta = 120^\circ \quad d = 1.64 \Omega$$

$$\text{The diameter of the mho unit is } (2 \times X'_d + 1.5 \times X_{TG}) = 10.29 \Omega.$$

$$\text{Impedance angle of the mho unit is } 90^\circ.$$

$$\text{MHO offset} = -2X'd = -7.2\Omega$$



78

BECKWITH ELECTRIC CO. INC.

78: Setting

Circle Diameter: 10.2 0.1 100.0 (Ohm) Disable
 Offset: -7.2 -100.0 100.0 (Ohm)
 Blinder Impedance: 1.6 0.1 50.0 (Ohm)
 Impedance Angle: 90 0 90 (Degree)
 Pole Slip Counter: 1 1 20
 Pole Slip Reset Time: 600 1 8160 (Cycles)
 Time Delay: β 1 8160 (Cycles)
 Trip on MHO Exit: Disable Enable

Outputs: 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23

Blocking Inputs: FL 1 2 3 4 5 6 7 8 9 10 11 12 13 14

Save Cancel

IPScm M-3400 Series (S-3400) (SERIAL)
 File Communication Monitor Relay Tools Windows Help
 Save Secondary Metering
 Monitor: Primary Metering & Status, Secondary Metering & Status, Accumulator Status, Phasor Diagram, Phase Distance, Loss of Field, **Out of Step**, Sync Scope, Function Status, 87 Dual Slope

Zoom in

Out of Step
 Zoom In Zoom Out

Positive Sequence Impedance (Ohm): 0
 Circle Diameter (Ohm): 10.2
 Circle Offset (Ohm): -7.2
 Circle Impedance Angle (Degree): 90
 Blinder Impedances (Ohm): 1.6
 Trip on MHO Exit: Enabled

BECKWITH ELECTRIC CO. INC.

Testing the 78 Element

- View Out of Step Monitor
- View Function Status
- Apply Pre-fault Values

Function Status
 87 Dual Slope
 Tripped

21 #1	32 #3	40/27	54F #2	81R #1
21 #2	40 #1	51V	54S	81R #2
21 #3	40 #2	51V	67N DT	87 #1
24 DT #1	40 VC#1	53 #1	67N IT	87 #2
24 DT #2	40 VC#2	53 #2	78	87GD
		53 #3	81 #1	87GS
		53 #4	81 #2	IPSL #1
		53N #1	81 #3	IPSL #2
		53N #2	81 #4	IPSL #3
		53N #3	81A #1	IPSL #4
		53X #1	81A #2	IPSL #5
		53X #2	81A #3	IPSL #6
DT #1	60FL	81A #4	8M	TC
DT #2	64B	81A #5		
	64F #1	81A #6		

1.4 kVA
 1.0 kΩ
 80.0 V
 8.0 A

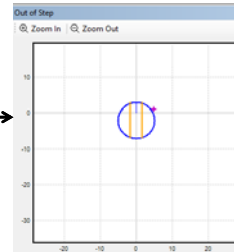
Set Mode: Analog Outputs

Set Mode	Direct	Frequency
VA	70.00 V	30.00 * 60.000 Hz
VB	0.000 V	0.00 * 60.000 Hz
VC	70.00 V	90.00 * 60.000 Hz
V Fault	2.000 V	0.00 * 180.000 Hz
neutral a	8.000 A	-10.00 * 60.000 Hz
neutral b	8.000 A	-130.00 * 60.000 Hz
neutral c	8.000 A	110.00 * 60.000 Hz

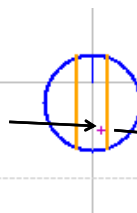
Testing the 78 Element

Rotate 3 ph currents up in 10 degree increments simultaneously

Analog Outputs			
Set Mode	Direct		
VA	70.00 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	70.00 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	8.000 A	-10.00 °	60.000 Hz
neutral b	8.000 A	-130.00 °	60.000 Hz
neutral c	8.000 A	110.00 °	60.000 Hz



Analog Outputs			
Set Mode	Direct		
VA	70.00 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	70.00 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	8.000 A	80.00 °	60.000 Hz
neutral b	8.000 A	-40.00 °	60.000 Hz
neutral c	8.000 A	200.00 °	60.000 Hz



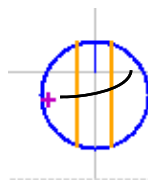
Function Status			
Function Pickup/Tripped		Pickup	Tripped
21 #1	32 #3	50/27	64F #2
21 #2	40 #1	51N	64S
21 #3	40 #2	51V	67N DT
24 D1 #1	40VC#1	59 #1	67N IT
24 DT #2	40VC#2	59 #2	78

78 Picks up when it hits the load blinder

Testing the 78 Element

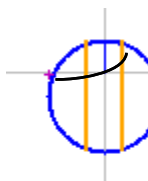
Continue to rotate 3 ph currents up in 10 degree increments

Analog Outputs			
Set Mode	Direct		
VA	70.00 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	70.00 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	8.000 A	150.00 °	60.000 Hz
neutral b	8.000 A	30.00 °	60.000 Hz
neutral c	8.000 A	270.00 °	60.000 Hz



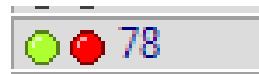
If we stop here before the boundary of the mho and go back, the target clears, no trip.

Analog Outputs			
Set Mode	Direct		
VA	70.00 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	70.00 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	8.000 A	180.00 °	60.000 Hz
neutral b	8.000 A	60.00 °	60.000 Hz
neutral c	8.000 A	300.00 °	60.000 Hz



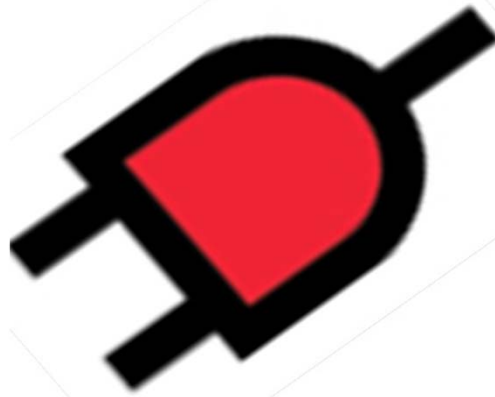
If we cross the boundary, the relay will trip within 2 to 3 cycles.

Binary Inputs / Trigger	
trip 1	<input checked="" type="checkbox"/> 2.304 cy

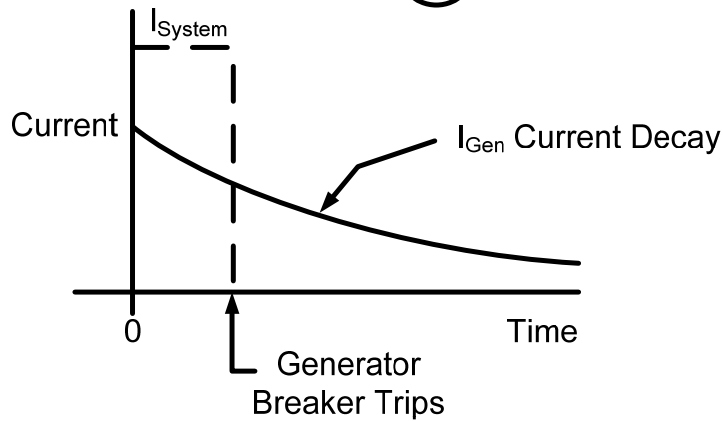
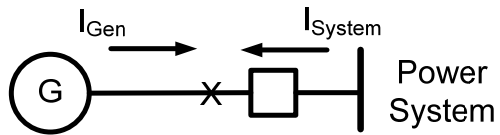


Stator Ground Fault (59N)

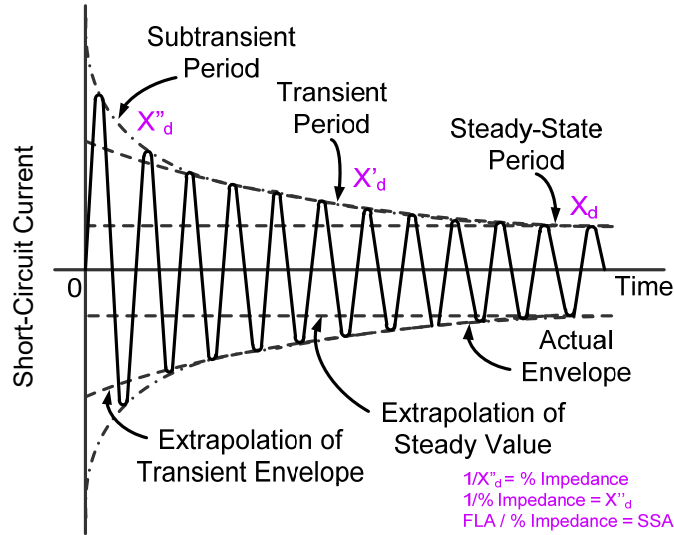
95% Stator Coverage



Generator Behavior During Short Circuits

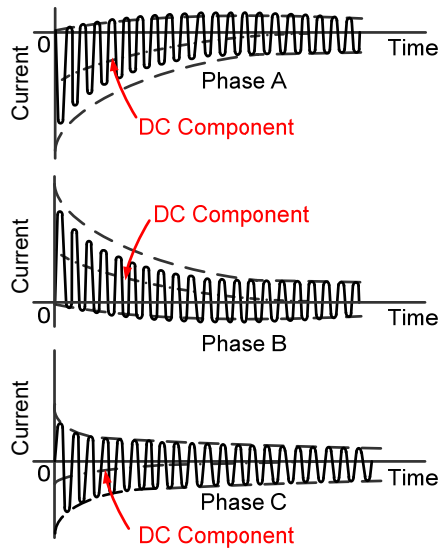


Generator Short-Circuit Current Decay



85

Effect of DC Offsets



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Grounding Techniques

➤ Why Ground?

- Improved safety by allowing detection of faulted equipment
- Stop transient overvoltages
 - Notorious in ungrounded systems
- Ability to detect a ground fault before a multiphase to ground fault evolves
- If impedance is introduced, limit ground fault current and associated damage faults
- Provide ground source for other system protection (other zones supplied from generator)

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Types of Generator Ground Fault Damage

- Following pictures show stator damage after an internal ground fault
- This generator was high impedance grounded, with the fault current less than 10A
- Some iron burning occurred, but the damage was repairable
- With low impedance grounded machines, the damage is severe

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Stator Ground Fault Damage



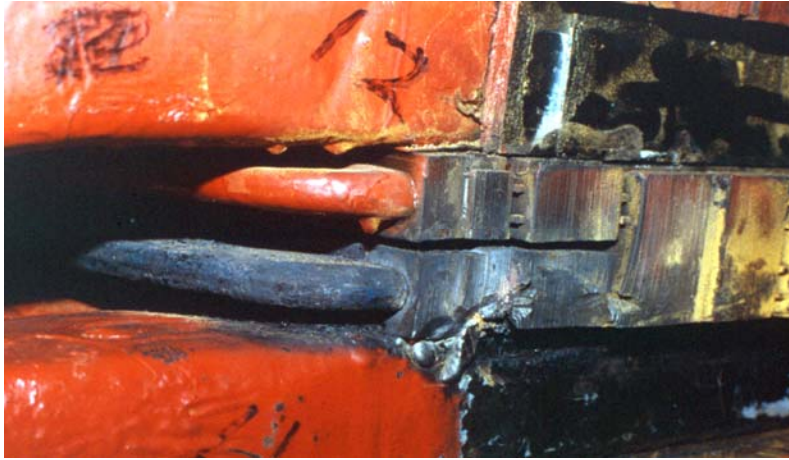
89

Stator Ground Fault Damage



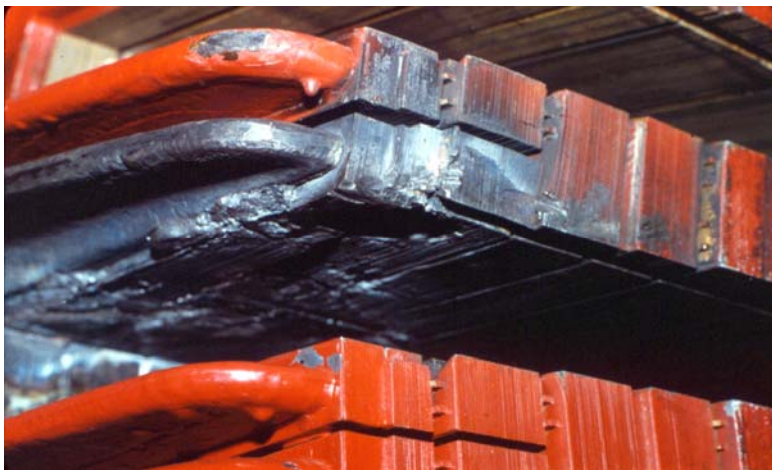
90

Stator Ground Fault Damage



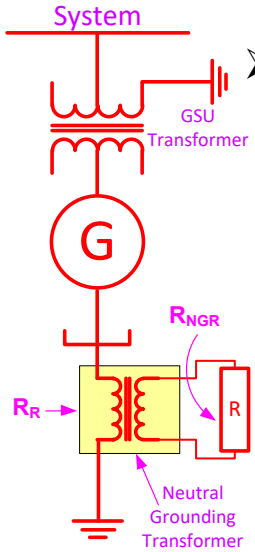
91

Stator Ground Fault Damage



92

Types of Generator Grounding

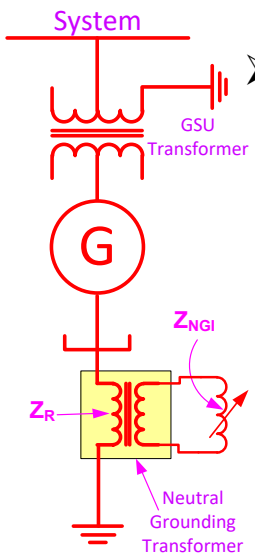


➤ High Impedance

- System ground source obtained from GSU
- Uses principle of reflected impedance
 - Eq: $R_{NGR} = R_R / [V_{pri}/V_{sec}]^2$
 - R_{NGR} = Neutral Grounding Resistor Resistance
 - R_R = Reflected Resistance
- Ground fault current typically $\leq 10A$

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Types of Generator Grounding



➤ Compensated

- Most expensive using tuned reactor
- System ground source obtained from GSU
- Uses reflected impedance from grounding transformer, same as high impedance grounded system does
- Generator damage mitigated from ground fault
- Reactor tuned against generator capacitance to ground to limit ground fault current to very low value (can be less than 1A)

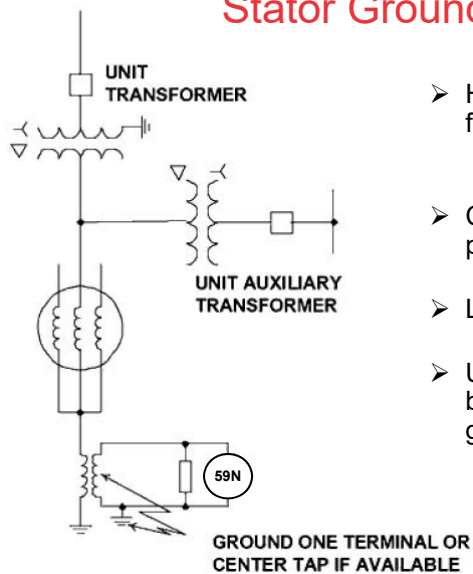
94

Stator Ground Fault-High Z Grounded Machines

- 95% stator ground fault provided by 59N
 - Tuned to the fundamental frequency
 - Must work properly from 10 to 80 Hz to provide protection during startup
- Additional coverage near neutral (last 5%) provided by:
 - 27TN: 3rd harmonic undervoltage
 - 59D: Ratio of 3rd harmonic at terminal and neutral ends of winding
- Full 100% stator coverage by 64S
 - Use of sub-harmonic injection
 - May be used when generator is off-line
 - Immune to changes in loading (MW, MVAR)

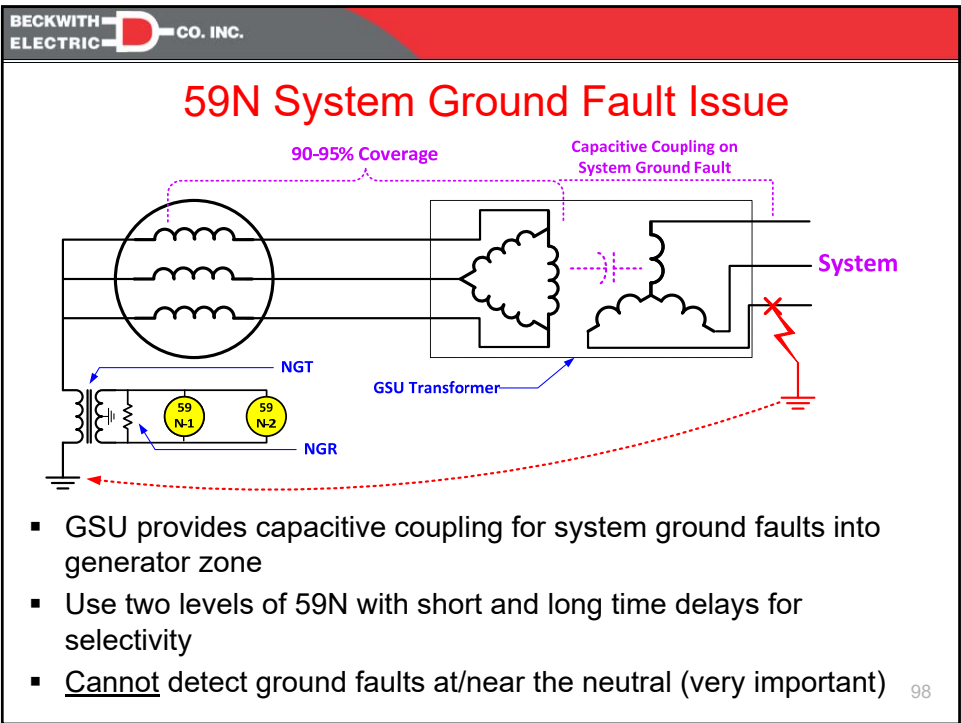
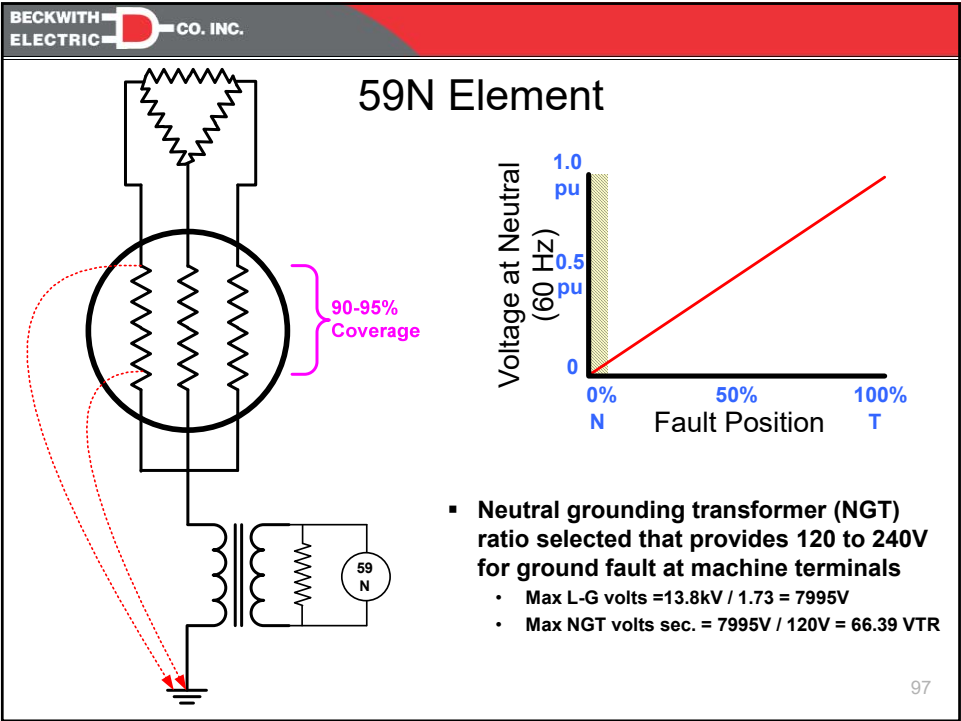
95

Stator Ground Fault (59N)



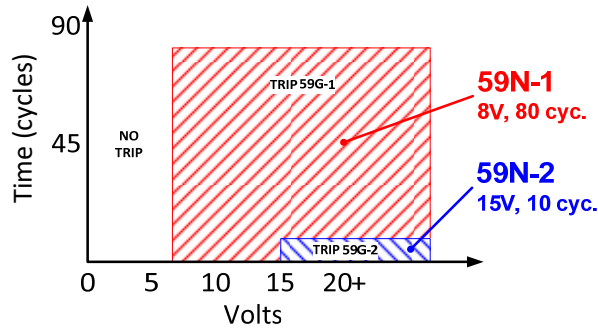
- High impedance ground limits ground fault current to about 10A
 - Limits damage on internal ground fault
- Conventional neutral overvoltage relay provides 90-95% stator coverage
- Last 5-10% near neutral not covered
- Undetected grounds in this region bypass grounding transformer, solidly grounding the machine!

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Multiple 59N Element Application

- **59N-1**, set in this example to 5%, may sense capacitance coupled out-of-zone ground fault
 - **Long** time delay



- **59N-2**, set in this example to 15%, is set above capacitance coupled out-of-zone ground fault
 - Short time delay

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Use of Symmetrical Component Quantities to Control 59N Tripping Speed

- A ground fault in the generator zone produces primarily zero sequence voltage
 - Negligible V_2 , I_2 or I_0
- A fault in the VT secondary or system (GSU coupled) generates negative sequence quantities in addition to zero sequence voltage
- The I_2 method may be employed to control the 59N for system ground faults
- The V_2/V_0 method may be employed to control the 59N for system and VT secondary ground faults

100

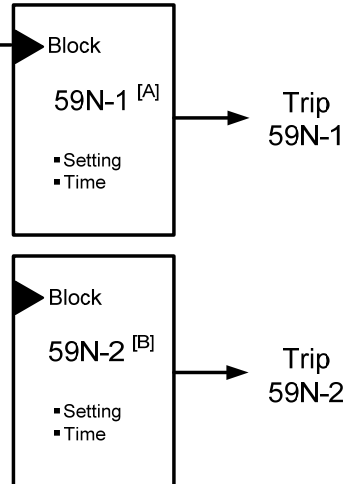
Use of I_2 to Control Fast 59N Element

$I_2 > 0.05$ pu

NOTES:

[A] 59N-1 is set sensitive and fast, using I_2 supervision to check for external ground faults and control (block) the element for external ground faults

[B] 59N-2 is set less sensitive and slower, therefore it will not operate for external ground faults.



I_2 is used to control 59N for ground faults on the high voltage side of the GSU

Use of V_2 / V_0 to Control Fast 59N Element

[C] $V_2 > 0.05$ pu

[D] $V_0 < 0.07$ pu

60FL Asserts

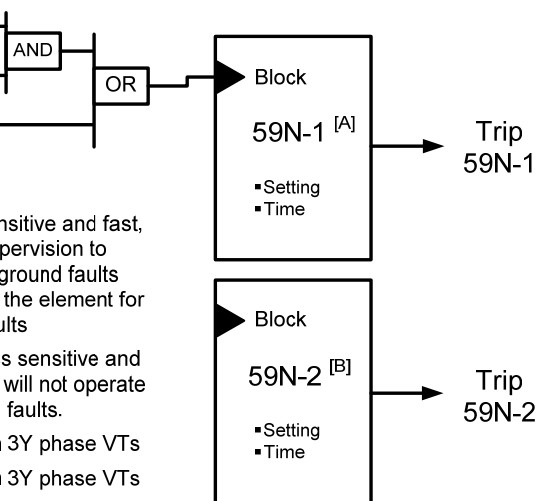
NOTES:

[A] 59N-1 is set sensitive and fast, using V_2 and V_0 supervision to check for external ground faults and control (block) the element for external ground faults

[B] 59N-2 is set less sensitive and slower, therefore it will not operate for external ground faults.

[C] V_2 derived from 3Y phase VTs

[D] V_0 derived from 3Y phase VTs



V_2 and V_0 is used to control 59N for ground faults on the high voltage side of the GSU and low voltage side of voltage transformers

Intermittent Arcing Ground Faults

- Can be very destructive, especially at neutral
- At neutral, even though AC current is very low, arcing fault develops a high voltage DC transient
- If enough arcs occur in a short time, destructive insulation damage can occur
- Conventional time delayed ground fault protection cannot protect for these events



Burned away copper of a fractured connection ring



Side of a bar deeply damaged by vibration sparking

Premature Failure of Modern Generators, Clyde V. Maughan

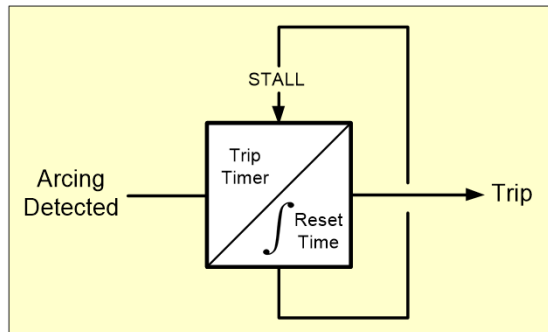
103

Intermittent Arcing Ground Fault



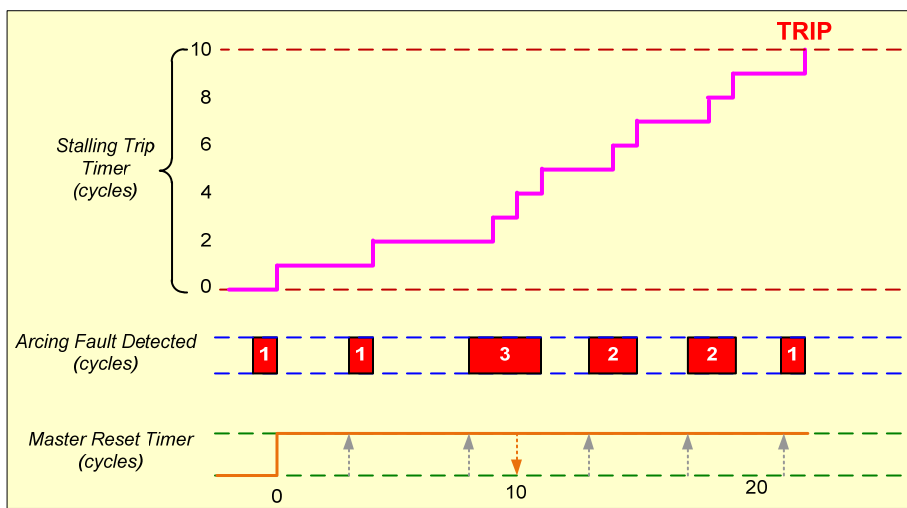
104

Intermittent Arcing Fault Timer Logic



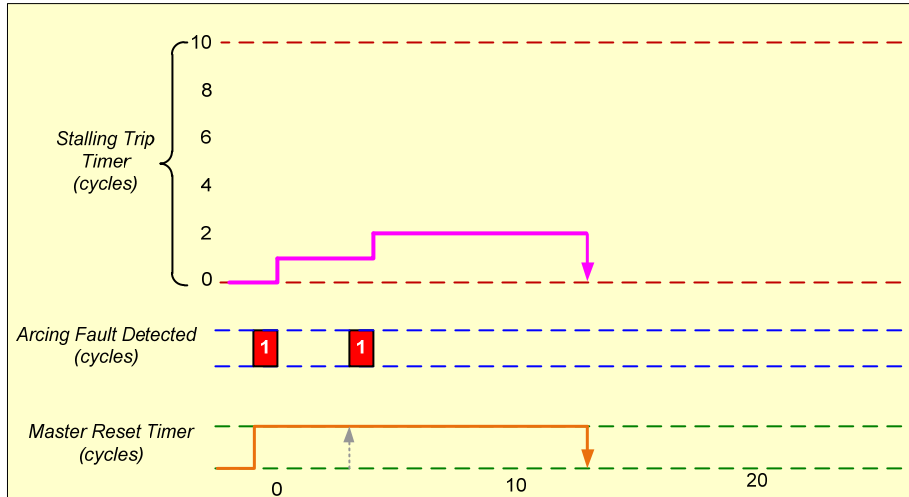
Stallable Trip Timer: Times Out to Trip
 Integrating Reset Time: Delays Reset for Interval

Intermittent Arcing Ground Fault



Arcing and Trip

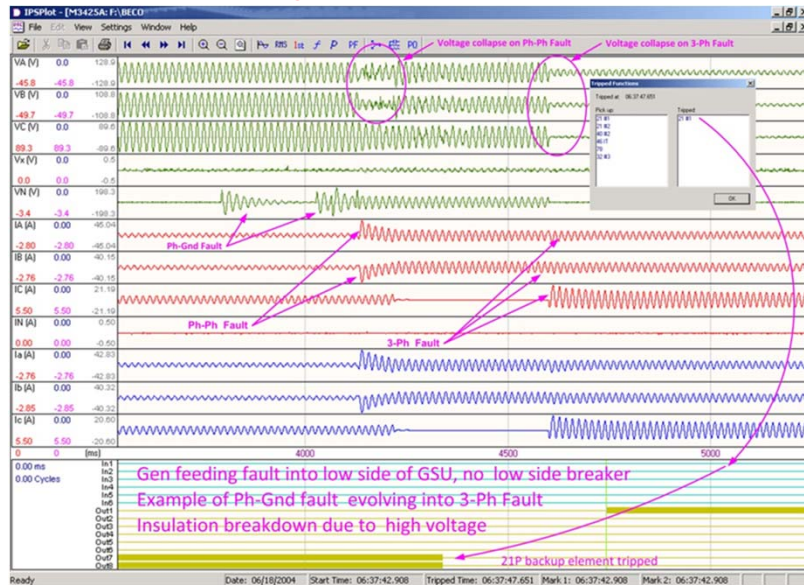
Intermittent Arcing Ground Fault



Arcing and Reset (No Trip)

107

Intermittent Arcing Ground Fault Turned Multiphase



108

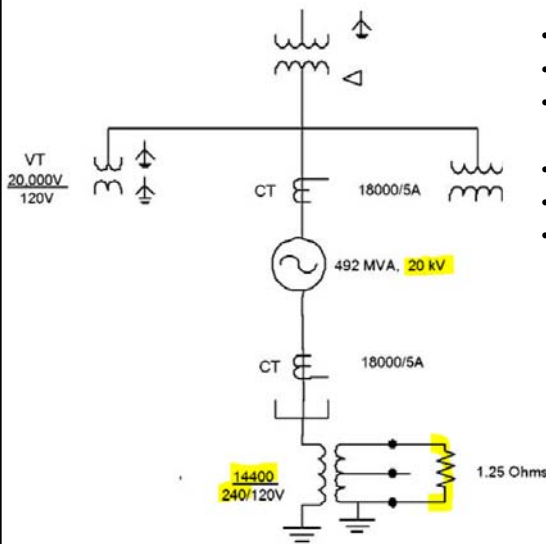
59N Element

59N – Generator Neutral Overvoltage: Three elements

- 1st set sensitive to cover down to 5% of stator
 - Long delay to coordinate with close-in system ground faults capacitively coupled across GSU, or,
 - Use V_2/V_0 or I_2 Control
- 2nd set higher than the capacitively coupled voltage so coordination from system ground faults is not necessary
 - Allows higher speed tripping
 - Only need to coordinate with PT fuses
- 3rd may be:
 - Set to initiate waveform capture and not trip
 - Used for intermittent arcing fault protection

109

59N: Setting



- $V_{LL} / 1.73 = V_{LG}$
- $20\text{kV} / 1.73 = 11,560\text{V}$
- $V_{LG} / \text{NGT Ratio} = 100\% \text{ Ground Fault Voltage}$
- $11,560\text{V} / (14,440\text{V}/240\text{V}) = 192$
- $5\text{V Setting} = 5/192 = 2.6\%$,
- $100\% - 2.6\% = 97.5\% \text{ Coverage}$

110

Setting up and viewing Oscillography

The screenshot shows the 'Relay' menu with 'Oscillograph' selected. The 'Setup Oscillograph Recorder' dialog box is open, showing settings for Partitions (4 Partitions: 168 Cycles) and Post Trigger Delay (20). The 'Trigger Outputs' section has output 8 checked. Annotations include: 'Manual trigger' pointing to the 'Trigger' option in the menu; 'Clear records' pointing to the 'Clear' option; and 'Assign output 8' pointing to the checked checkbox for output 8.

111

Testing the 59G,N Element, Setting # 1,3

The screenshot shows the 'Secondary Metering & Status' window. On the left, 'Voltages (V)' are listed: AB (119.8), BC (119.7), CA (119.7), Neutral (4.0), Pos. Seq. (119.8), Neg. Seq. (0.0), Zero Seq. (0.0), and VX (0.0). On the right, 'Analog Outputs' are listed with Set Mode 'Direct'. An arrow points from the 'V A-N' voltage reading to the 'V A-N' analog output setting.

Pick-up test:

- Start with pre-fault
- Ramp in .1V steps
- Look for target

Timing test:

- Start with pre-fault
- Jump to 6V
- Check timing output 1
- Check timing output 8 (osc)

Pick up #1

Set Mode	Direct		
V A-N	120.0 V	30.00 *	60.000 Hz
V B-N	0.000 V	-120.00 *	60.000 Hz
V C-N	120.0 V	90.00 *	60.000 Hz
I A	3.000 A	0.00 *	60.000 Hz
I B	3.000 A	-120.00 *	60.000 Hz
I C	3.000 A	120.00 *	60.000 Hz
V Fault	5.500 V	0.00 *	60.000 Hz

Timing #1

Set Mode	Direct		
V A-N	120.0 V	30.00 *	60.000 Hz
V B-N	0.000 V	-120.00 *	60.000 Hz
V C-N	120.0 V	90.00 *	60.000 Hz
I A	3.000 A	0.00 *	60.000 Hz
I B	3.000 A	-120.00 *	60.000 Hz
I C	3.000 A	120.00 *	60.000 Hz
V Fault	6.000 V	0.00 *	60.000 Hz

Timing #3

Set Mode	Direct		
V A-N	120.0 V	30.00 *	60.000 Hz
V B-N	0.000 V	-120.00 *	60.000 Hz
V C-N	120.0 V	90.00 *	60.000 Hz
I A	3.000 A	0.00 *	60.000 Hz
I B	3.000 A	-120.00 *	60.000 Hz
I C	3.000 A	120.00 *	60.000 Hz
V Fault	6.000 V	0.00 *	60.000 Hz

112

Outputs
1

Binary Inputs / Trigger
Trip 92.06 cy

Trip 15.73 cy

Testing the 59G,N Element, Setting # 2

Pre-fault settings

Voltages (V)	
AB	119.8
BC	119.7
CA	119.7
Neutral	14.4
Pos. Seq.	119.9
Neg. Seq.	0.0
Zero Seq.	0.0
VX	0.0

Analog Outputs			
Set Mode	Direct		
V A-N	120.0 V	30.00 *	60.000 Hz
V B-N	0.000 V	-120.00 *	60.000 Hz
V C-N	120.0 V	90.00 *	60.000 Hz
I A	3.000 A	0.00 *	60.000 Hz
I B	3.000 A	-120.00 *	60.000 Hz
I C	3.000 A	120.00 *	60.000 Hz
V Fault	14.50 V	0.00 *	60.000 Hz

- Pick-up test:**
- Start with pre-fault
 - Ramp in .1V steps
 - Look for target output 2

- Timing test:**
- Start with pre-fault
 - Jump to 16V
 - Check timing output 2

Pick up #2

Analog Outputs			
Set Mode	Direct		
V A-N	120.0 V	30.00 *	60.000 Hz
V B-N	0.000 V	-120.00 *	60.000 Hz
V C-N	120.0 V	90.00 *	60.000 Hz
I A	3.000 A	0.00 *	60.000 Hz
I B	3.000 A	-120.00 *	60.000 Hz
I C	3.000 A	120.00 *	60.000 Hz
V Fault	15.00 V	0.00 *	60.000 Hz

Outputs	
1	2

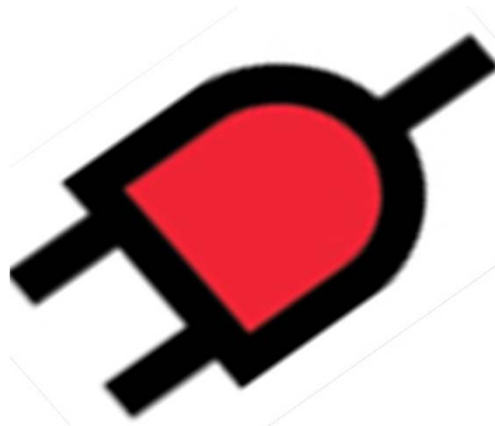
Timing #2

Analog Outputs			
Set Mode	Direct		
V A-N	120.0 V	30.00 *	60.000 Hz
V B-N	0.000 V	-120.00 *	60.000 Hz
V C-N	120.0 V	90.00 *	60.000 Hz
I A	3.000 A	0.00 *	60.000 Hz
I B	3.000 A	-120.00 *	60.000 Hz
I C	3.000 A	120.00 *	60.000 Hz
V Fault	16.00 V	0.00 *	60.000 Hz

Trip 2 21.37 cy

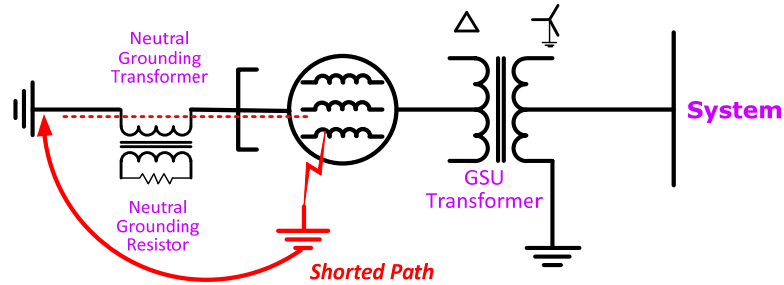
113

Stator Ground Fault (27TN) 5% Stator Coverage, Near Neutral



114

Why Do We Care About Faults Near Neutral?

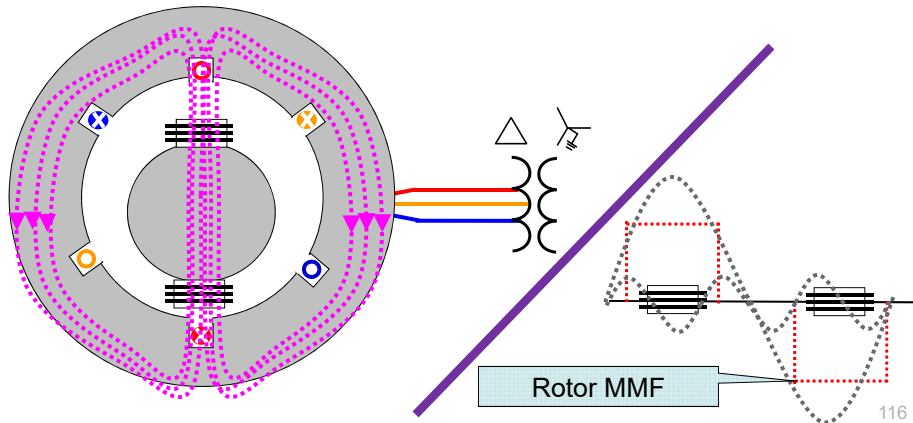


- A fault at or near the neutral shunts the high resistance that saves the stator from large currents with an internal ground fault
- A generator operating with an undetected ground fault near the neutral is an accident waiting to happen
- We can use 3rd Harmonic or Injection Techniques for complete (100%) coverage

115

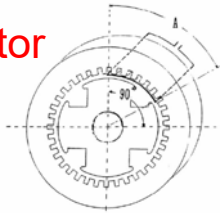
Third-Harmonic Rotor Flux

- Develops in stator due to imperfections in winding and system connections
- Unpredictable amount requiring field observation at various operating conditions
- Also dependent on pitch of the windings, which a method to define the way stator windings placed in the stator slots

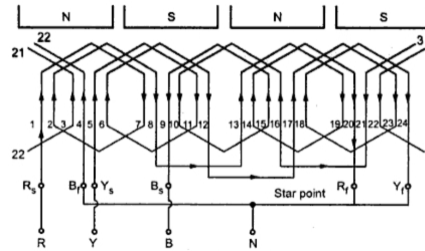
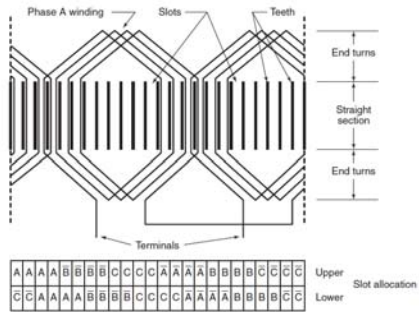


116

Generator Pitch



Pole spans 60 over 90 = 2/3 pitch



Pitch Factor is calculated by dividing the coil throw (-) 1 (coil span), by the number of slots per pole.

Using the examples in 1 through 3 above:

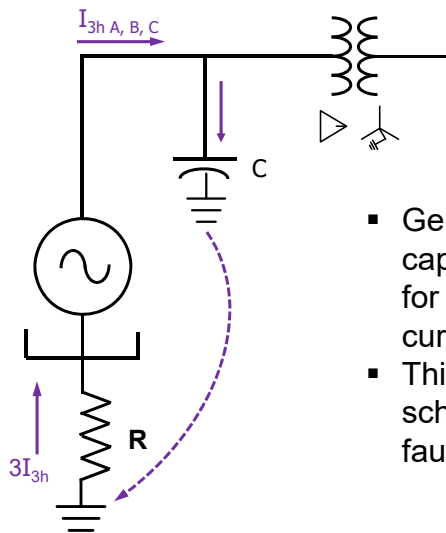
$$\text{Pitch Factor} = \frac{1 \text{ to } 9 \text{ throw } (-) 1}{48 \text{ Slots} \div 4 \text{ Poles}} = \frac{8}{12}$$

Pitch Factor = 2/3

Stator Winding Diagram Illustrating "Pitch" In Winding Construction

117

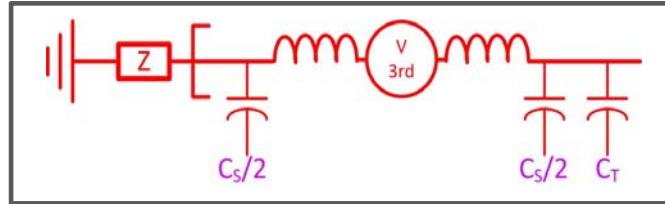
Using Third Harmonic in Generators



- Generator winding and terminal capacitances (C) provide path for the third-harmonic stator current via grounding resistor
- This can be applied in protection schemes for enhanced ground fault protection coverage

118

Generator Capacitance and 3rd Harmonics

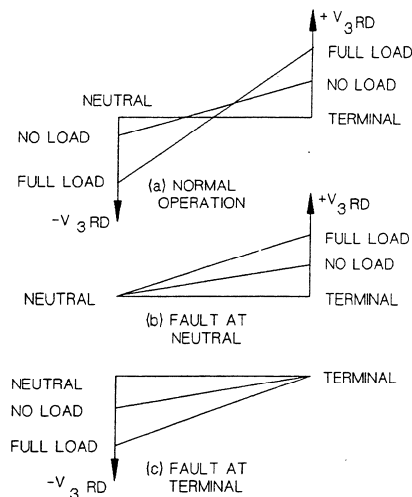


- 3rd harmonics are produced by some generators
 - Amount typically small
 - Lumped capacitance on each stator end is $C_s/2$.
 - C_T is added at terminal end due to surge caps and isophase bus
 - Effect is 3rd harmonic null point is shifted toward terminal end and not balanced

119

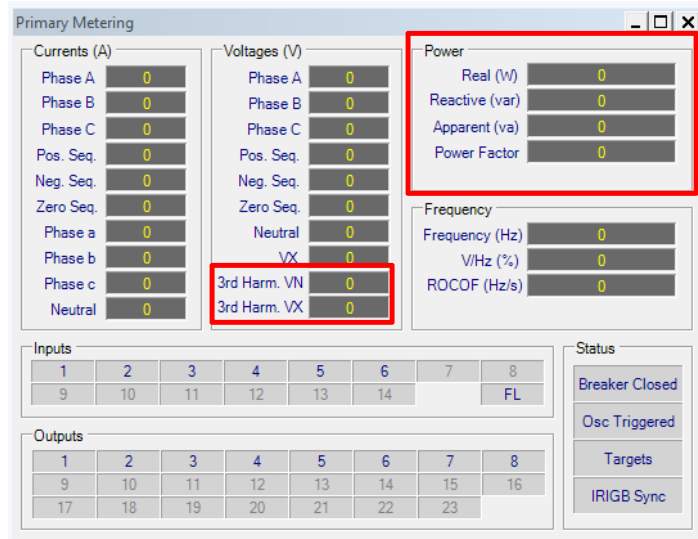
3rd Harmonic in Generators

- 3rd harmonic may be present in terminal and neutral ends
- Useful for ground fault detection near neutral
 - If 3rd harmonic goes away, conclude a ground fault near neutral
- 3rd harmonic varies with loading



120

3rd Harmonic Voltages and Ratio Voltage



121

27TN – 3rd Harmonic Neutral Undervoltage

- Provides 0-15% stator winding coverage (typ.)
- Tuned to 3rd harmonic frequency
- Provides two levels of setpoints
- Supervisions for increased security under various loading conditions: Any or All May be Applied Simultaneously
 - Phase Overvoltage Supervision
 - Underpower Block
 - Forward & Reverse
 - Under VAr Block; Lead & Lag
 - Power Factor Block; Lead & Lag
 - Definable Power Band Block
 - Undervoltage/No Voltage Block
 - Varies with load
 - May vary with power flow direction
 - May vary with level
 - May vary with lead and lag
 - May be gaps in output

Loading/operating variables may be Sync Condenser, VAr Sink, Pumped Storage, CT Starting, Power Output Reduction

122

3rd Harmonic in Generators: Typical 3rd Harmonic Values

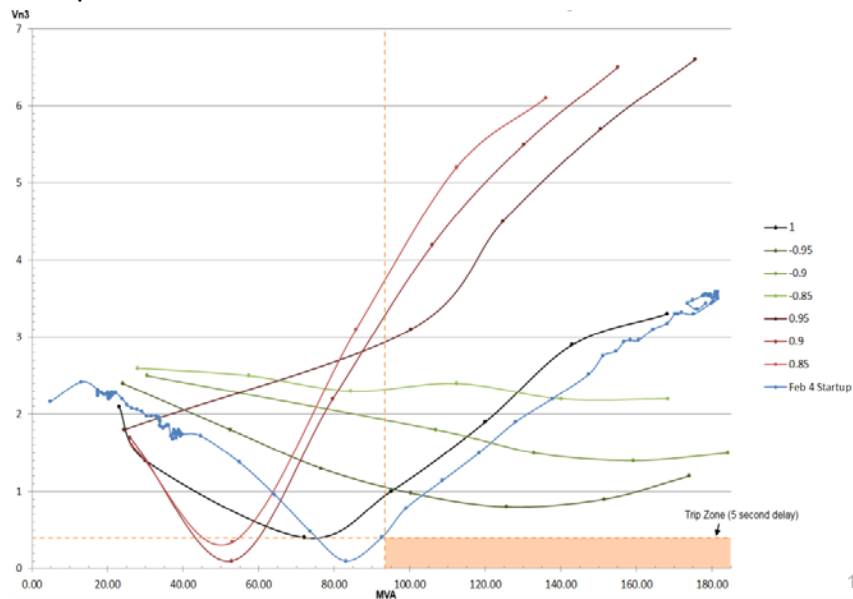
UNIT LOAD		180 HZ RMS VOLTAGE		VOLTAGE RATIO
MW	MVAR	NEUTRAL	TERMINAL	TERMINAL/NEUTRAL
0	0	2.8	2.7	1.08
7	0	2.5	3.7	1.48
35	5	2.7	3.8	1.41
105	5	4.2	5.0	1.19
175	25	5.5	6.2	1.13
340	25	8.0	8.0	1.00

Magnitudes of Third Harmonic Voltages
for a Typical Generator

- 3rd harmonic values tend to increase with power and VAR loading
- Fault near neutral causes 3rd harmonic voltage at neutral to go to zero volts

123

Example 3rd Harmonic Plot: Effects of MW and MVAR Loading



124

27TN Settings and Supervision

27TN: Third Harmonic Undervoltage, Neutral

#1 | #2

Pickup: 1.25 0.10 14.00 (V)

Pos. Seq. Voltage Block: 90 5 180 (V) Disable Enable

Forward Power Block: 0.20 0.01 1.00 (PU) Disable Enable

Reverse Power Block: -0.05 -1.00 -0.01 (PU) Disable Enable

Lead var Block: -0.10 -1.00 -0.01 (PU) Disable Enable

Lag var Block: 0.05 0.01 1.00 (PU) Disable Enable

Lead Power Factor Block: 0.05 0.01 1.00 (Lead) Disable Enable

Lag Power Factor Block: 0.05 0.01 1.00 (Lag) Disable Enable

Hi Band Forward Power Block: 0.05 0.01 1.00 (PU) Disable Enable

Lo Band Forward Power Block: 0.05 0.01 1.00 (PU)

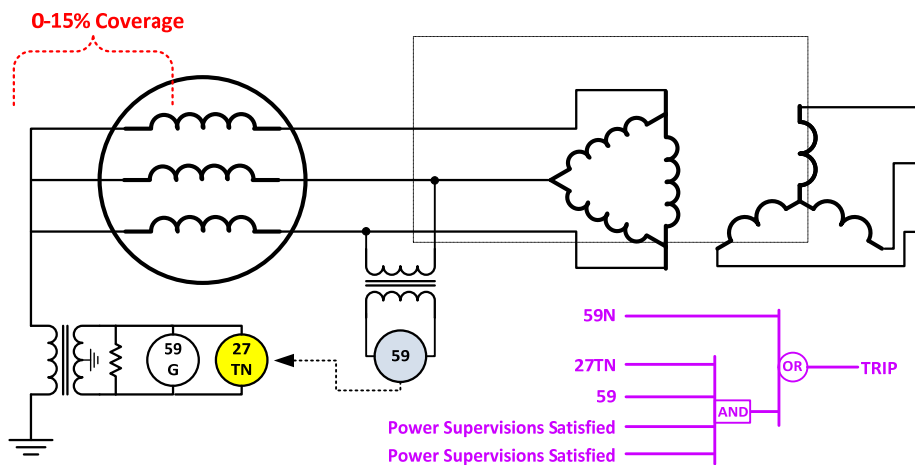
Time Delay: 300 1 8160 (Cycles)

Outputs: 1 2 3 4 5 6 7 8
 9 10 11 12 13 14 15 16
 17 18 19 20 21 22 23

Blocking Inputs: FL 1 2 3 4
 5 6 7 8 9
 10 11 12 13 14

125

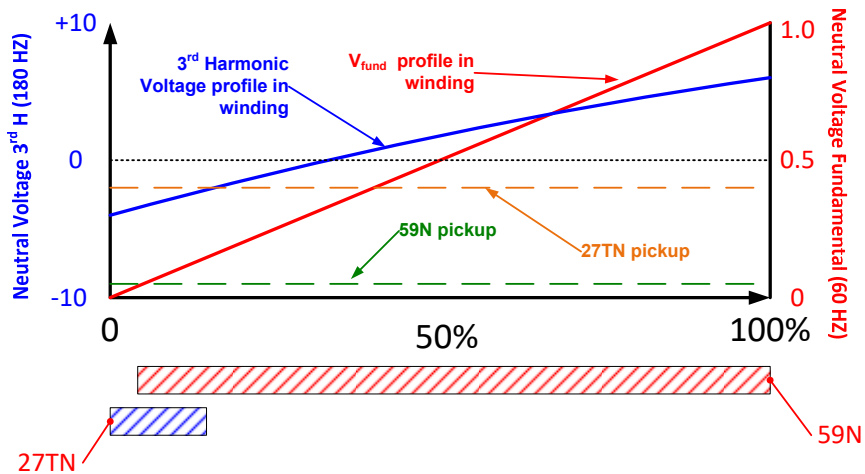
100% Stator Ground Fault (59N/27TN)



Third-Harmonic Undervoltage Ground-Fault Protection Scheme

126

100% Stator Ground Fault (59N/27TN)



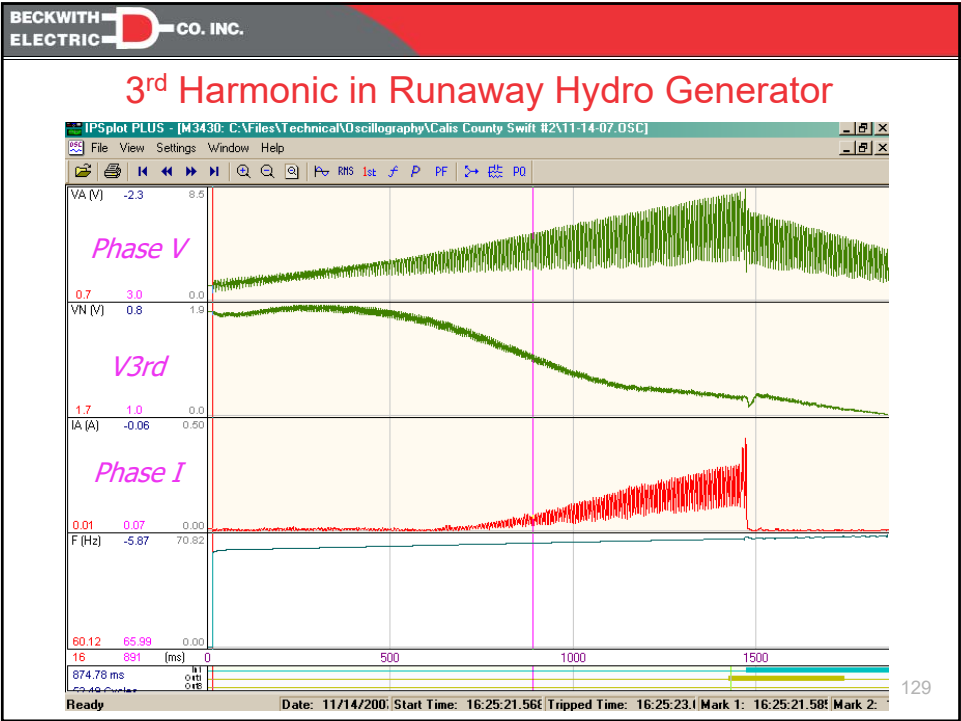
Overlap of Third Harmonic (27TN) with 59N Relay

127

3rd Harmonic Voltage Decrease During an Over Speed Condition in a 45MW Hydro Generator

- Typical value of 3rd harmonic (V_{3rd}) is around 1.7V, 27TN set to pick up at 1.1V.
- A line breaker tripped isolating plant, and they experienced a 27TN operation.
- Oscillograph shows the V_{3rd} decreased from 1.7V to 1.0V as the frequency went from 60 Hz to 66Hz, (only 110% over speed).
- This is well below the 180-200% over speed condition that is often cited as possible with hydros upon full load rejection.
- What happens to 59N?

128



129

BECKWITH ELECTRIC CO. INC.

27TN: Setting

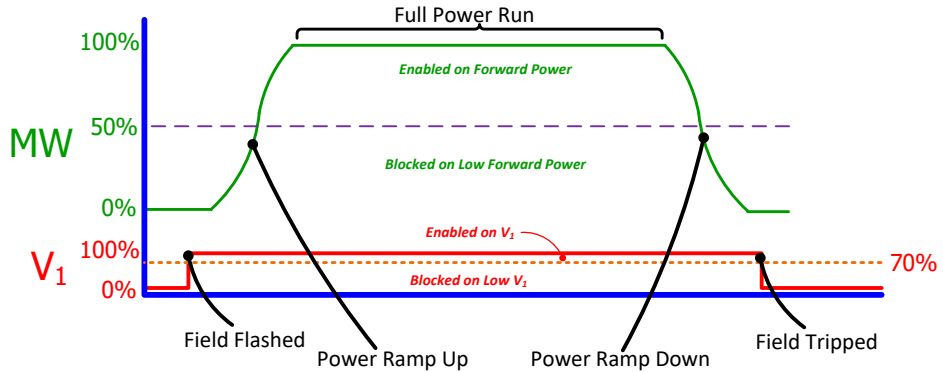
Table A.1—Measured primary third harmonic neutral voltages

MVA	Mvar	Measured primary third harmonic voltages					Secondary Neutral Voltage	Secondary Neutral Voltage
		X-phase	Y-phase	Z-phase	Average phase volts	Neutral voltage		
20% @ 246 MVA	0	66.0	69.7	64.2	66.6	-18.9	0.32	1.25
	80	80.7	84.3	88.0	84.3	-52.4	0.87	
	98	89.8	93.5	97.2	93.5	-56.8	0.95	
	126	104.5	119.2	117.3	113.7	-81.1	1.35	
	147	128.3	130.2	122.8	127.1	-94.0	1.57	
	174	135.7	143.0	141.2	139.9	-108.2	1.80	
50% @ 246 MVA	201	165.0	161.3	155.8	160.7	-117.9	1.97	2.5
	227	179.7	179.7	181.5	180.3	-146.4	2.44	
	384	242.0	238.3	236.5	239.0	-191.3	3.18	
	408	242.0	249.3	240.2	243.8	-198.9	3.37	
	447	265.8	247.5	251.2	254.8	-207.5	3.46	
	482	276.8	276.8	258.5	270.7	-217.0	3.67	

130

27TN: Setting

27TN Blocking



131

27TN: Setting

27TN: Third Harmonic Undervoltage, Neutral

Pickup:	1.25	0.10	14.00 (V)	Disable
Pos. Seq. Voltage Block:	84	5	180 (V)	Disable <input checked="" type="radio"/> Enable
Forward Power Block:	0.50	0.01	1.00 (PU)	Disable <input checked="" type="radio"/> Enable
Reverse Power Block:	-1.00	-1.00	-0.01 (PU)	<input checked="" type="radio"/> Disable <input type="radio"/> Enable
Lead var Block:	-1.00	-1.00	-0.01 (PU)	<input checked="" type="radio"/> Disable <input type="radio"/> Enable
Lag var Block:	1.00	0.01	1.00 (PU)	<input checked="" type="radio"/> Disable <input type="radio"/> Enable
Lead Power Factor Block:	1.00	0.01	1.00 (Lead)	<input checked="" type="radio"/> Disable <input type="radio"/> Enable
Lag Power Factor Block:	1.00	0.01	1.00 (Lag)	<input checked="" type="radio"/> Disable <input type="radio"/> Enable
Hi Band Forward Power Block:	0.60	0.01	1.00 (PU)	<input checked="" type="radio"/> Disable <input type="radio"/> Enable
Lo Band Forward Power Block:	0.50	0.01	1.00 (PU)	
Time Delay:	90	1	8160 (Cycles)	

Outputs: 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23

Blocking Inputs: FL 1 2 3 4 5 6 7 8 9 10 11 12 13 14

Save Cancel

132

Testing the 27TN Element

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	50.000 Hz
neutral b	3.950 A	-120.00 °	50.000 Hz
neutral c	3.950 A	120.00 °	50.000 Hz

Pre-fault Condition

133

Testing the 27TN Element

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	50.000 Hz
neutral b	3.950 A	-120.00 °	50.000 Hz
neutral c	3.950 A	120.00 °	50.000 Hz

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	1.250 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

Pre-fault Condition

Ramp V Fault down in .25V steps

Outputs	
1	
9	
17	

Find the Pick-up

Verify with Metering Screen (relay)

134

Testing the 27TN Element

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

Pre-fault Condition

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	1.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

Fault Condition

trip 1    91.87 cy

Check Timing

135

Testing the 27TN Element, Positive Seq. Voltage

Pre-fault Condition

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

Fault Condition

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	1.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

Lower 3 ph Voltage in 1V steps

Analog Outputs			
Set Mode	Direct		
VA	84.00 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	84.00 V	90.00 °	60.000 Hz
V Fault	1.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

- Voltages (V)	
AB	83.8
BC	83.7
CA	83.7
Neutral	0.0
Pos. Seq.	83.8
Neg. Seq.	0.0
Zero Seq.	0.0
VX	0.0

Outputs

1 2

Monitor positive Seq. Voltage

Contact drops out

136

Testing the 27TN Element, Forward Power Block

Pre-fault Condition

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	2.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

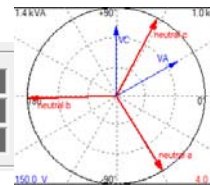
Fault Condition

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	1.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	0.00 °	60.000 Hz
neutral b	3.950 A	-120.00 °	60.000 Hz
neutral c	3.950 A	120.00 °	60.000 Hz

Rotate 3 ph current angles
1degree steps

Analog Outputs			
Set Mode	Direct		
VA	120.0 V	30.00 °	60.000 Hz
VB	0.000 V	0.00 °	60.000 Hz
VC	120.0 V	90.00 °	60.000 Hz
V Fault	1.000 V	0.00 °	180.00 Hz
neutral a	3.950 A	-58.00 °	60.000 Hz
neutral b	3.950 A	-178.00 °	60.000 Hz
neutral c	3.950 A	62.00 °	60.000 Hz

Power (p.u.)	
Real	0.497
Reactive	0.864
Apparent	0.994

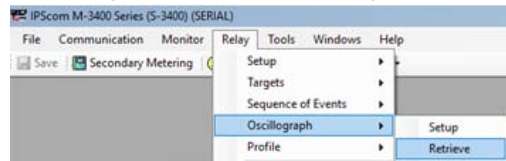


Monitor real power

Contact drops out

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Setting up and viewing Oscillography



Retrieve Record

Save as *.osc or *.cfg

Load and View in BecoPlot Software

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BECKWITH ELECTRIC CO. INC.

SOE Viewer

View Sequence of Events Record Close

Open Print Print Preview Set Print Range

No	Event Summary	Item	Value	Unit
1	01/01/2001, 01:01:80.000 50/27: Pickup/Timeout/	VA	46.3	V
2	01/01/2001, 01:01:80.000 50/27: Drop	VB	46.3	V
3	01/01/2001, 01:01:80.000	VC	46.3	V
4	01/01/2001, 01:01:80.000	VN	0.0	V
5	01/01/2001, 01:01:80.000 50/27: Pickup/Timeout/	VX	0.0	V
6	01/01/2001, 01:01:80.000	VPS	46.5	V
7	01/01/2001, 01:01:80.000	VNS	0.1	V
8	01/01/2001, 01:01:80.000 50/27: Pickup/Timeout/	VZS	0.1	V
9	01/01/2001, 01:01:80.000 50/27: Drop	IA	0.00	A
		IB	0.00	A
		IC	0.00	A
		IN	0.00	A
		Ia	4.50	A
		Ib	4.49	A
		Ic	4.48	A
		IPS	4.49	A
		INS	0.00	A
		IZS	0.00	A
		Ia Diff	4.49	A

#8

Inputs Pickup

FL 1 2 3 4 5
 6 7 8 9 10 11
 12 13 14

Inputs Drop

FL 1 2 3 4 5
 6 7 8 9 10 11
 12 13 14

Outputs Pickup

1 2 3 4 5 6
 7 8 9 10 11 12
 13 14 15 16 17 18
 19 20 21 22 23

Outputs Drop

1 2 3 4 5 6
 7 8 9 10 11 12
 13 14 15 16 17 18
 19 20 21 22 23

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Oscillography Recorder

Setup Oscillograph Recorder Close

Settings

Partitions: 16 Partitions: 48 Cycles

Post Trigger Delay: 5 5 95 (%)

Trigger Inputs

1 2 3 4 5 6 7 8
 9 10 11 12 13 14

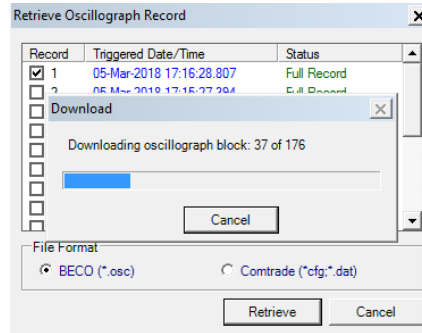
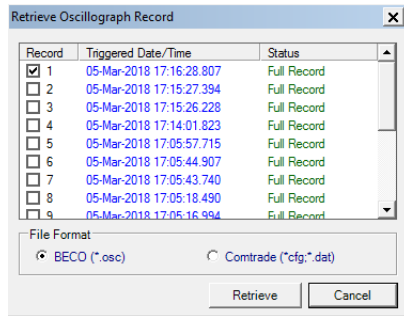
Trigger Outputs

1 2 3 4 5 6 7 8
 9 10 11 12 13 14 15 16
 17 18 19 20 21 22 23

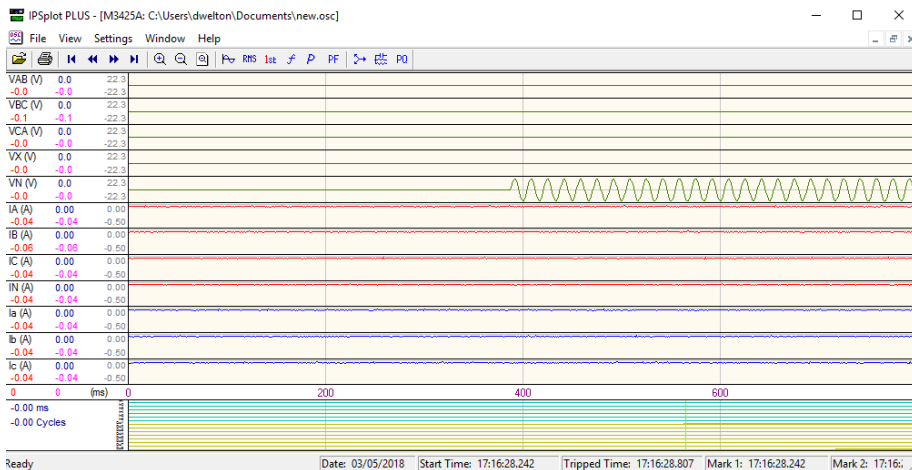
Save Cancel

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Retrieve Record



Oscillography-IPsplot Plus



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